

Lecture 6 – 09/04/2015

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- Continuous-Time LTI Systems: The Convolution Integral
 - o Introduction

- Stair-Case Approximation
 - o Equations 2.25 and 2.26
 - o Figure 2.13
 - o Equations 2.27 as an idealization

- Convolution Integral Representation of LTI Systems
 - o Figure 2.15
 - o Equations 2.30, 2.31, and 2.33

- Examples 2.7 – 2.9
 - o Reading Assignment
 - Example 2.9