

Spring, 2022

# ME 597 – Solid Mechanics II

## Lecture 1

### Introduction to vectors and tensors

KEEP A MASK WITH  
YOU AT ALL TIMES



**PROTECT  
PURDUE**



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# What is a tensor?

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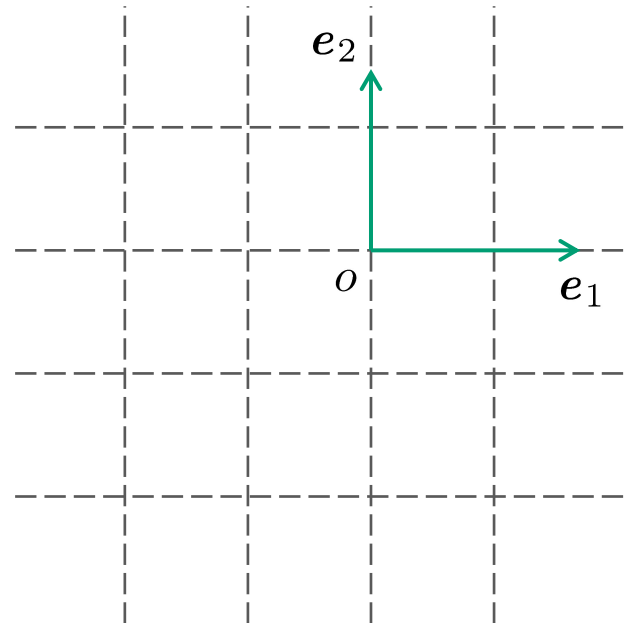
- Tensors are abstract mathematical entities.
- Vectors are *first order* tensors.
- Vectors and tensors exist separately of a particular coordinate system (i.e., they are coordinate invariant).

... so let's start by reviewing Vector Algebra.

# Vector algebra

## Coordinate systems

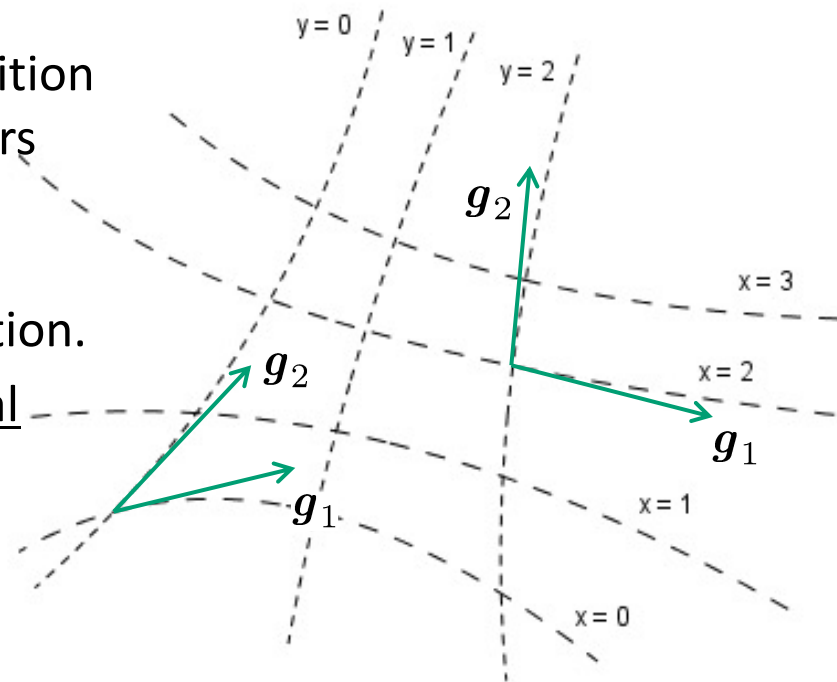
- An origin (relative to which positions are measured)
- A set of coordinate curves (that correspond to paths through space along which all but one of the coordinates are constant)



# Vector algebra

## Coordinate systems

- An origin (relative to which positions are measured)
- A set of coordinate curves (that correspond to paths through space along which all but one of the coordinates are constant)
- Basis are defined at each position in space as the tangent vectors to the coordinate curves. Therefore, basis vectors  $\{g_i\}$  change from position to position.
- Basis  $\{g_i\}$  are non-orthogonal in general.



## Coordinate systems

- If the coordinate curves are straight lines, then the system is a rectilinear coordinate system.
- If the basis vectors of a rectilinear coordinate system are orthogonal then the system is a Cartesian coordinate system.
- If the basis vectors (or axes) of a Cartesian coordinate system are unit vectors  $\{e_i\}$  then the basis are called orthonormal and follow the condition

$$e_i \cdot e_j = \delta_{ij}$$

- We will choose basis vectors that form a right-handed triad

$$e_i \times e_j = \epsilon_{ijk} e_k$$

What is the component of a vector (or the coordinate of a position vector) along a basis vector direction?

DIY

# Vector algebra

## Change of basis

- Two orthonormal bases  $\{e_\alpha\}$  and  $\{e'_i\}$
- The goal is to change bases from  $\{e_\alpha\}$  to  $\{e'_i\}$ , that is to write  $\{e'_i\}$  as a linear combination of  $\{e_\alpha\}$ .
- A linear transformation matrix  $Q$  is then defined as

$$e'_i = \sum_{\alpha=1}^3 Q_{i\alpha} e_\alpha \qquad Q_{i\alpha} = e'_i \cdot e_\alpha$$

Let's write the transformation using a column-matrix notation.

Show the following properties:

$$Q^T = Q^{-1}$$

$$\det(Q)$$

DIY

# Introduction to vectors and tensors

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Any questions?