Lecture 20 Structural elements: beams, plates, shells



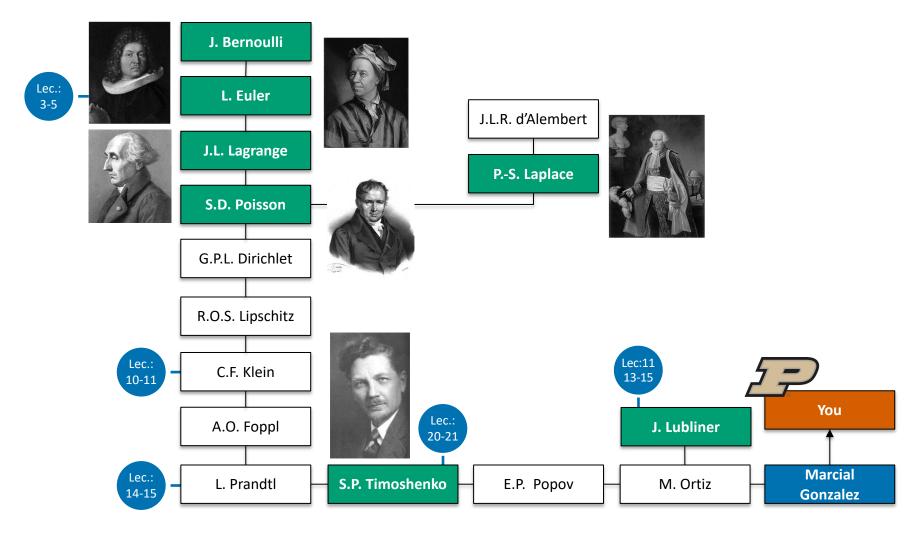


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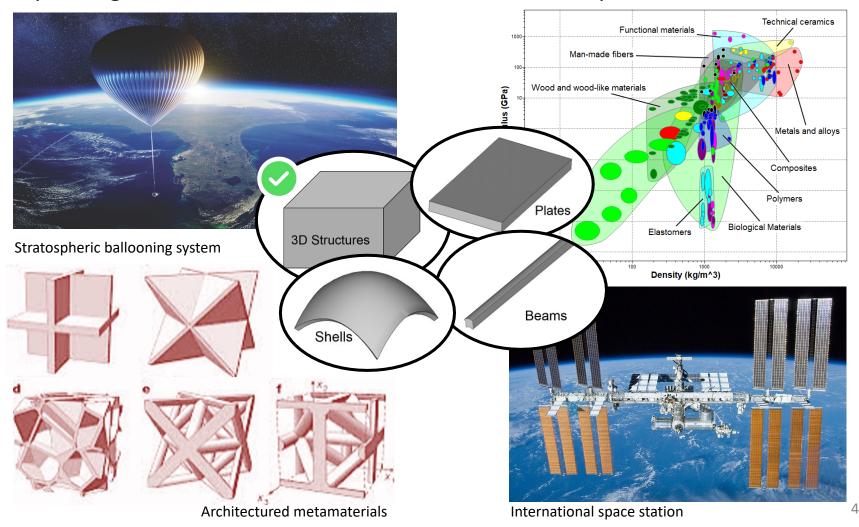
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General information

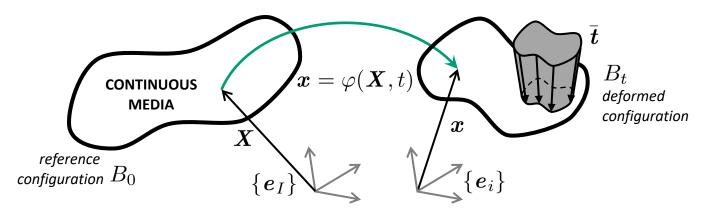
Know your history genealogy



Formulation of structural elements (beams, plates, shells) as the analytical upscaling of continuum solids under kinematic assumptions.



Formulation of structural elements (beams, plates, shells) as the analytical upscaling of continuum solids under kinematic assumptions.

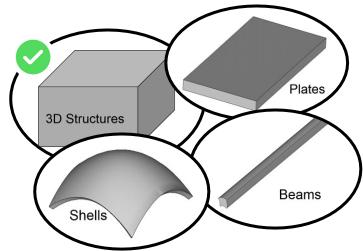


Linearized kinematic – Small trains

- The linearization is evaluated in the undeformed configuration (i.e., $m{X} o m{X} + m{u}(m{X})$ and $m{F} = m{I}, \, \nabla_0 m{u} = \nabla m{u}$): $\langle \nabla_\varphi m{E}; m{u} \rangle = \frac{1}{2} [\nabla m{u} + (\nabla m{u})^T] = m{\epsilon} \qquad \begin{array}{c} \text{small-strain tensor} \\ \text{(employed in elasticity theory)} \end{array}$
- Simplified geometry
- Simplifying kinematic assumptions (i.e., simplified displacement field ${m u}=(u_1,u_2,u_3)$)

Simplified geometry

- Many everyday engineering applications utilize structural members such as rods, beams, cables, plates, and shells.
- Structural members can be idealized as one-dimensional (rods, beams, and cables) and two-dimensional (plates and shells) members.
- Assumption: two dimensions
 (in the case of beams) or
 one dimension (in the case of
 plates and shells) are significantly
 smaller than the other dimensions.



 Stress-strain behavior is upscaled to a relationship between internal resultants and kinematic variables (of the mid-plane).

Timoshenko beams

- Kinematic assumptions, with $\bar{w} \ll h$

$$u_1(x, z) = \bar{u}(x) + z\theta_2(x)$$
$$u_2 = 0$$
$$u_3(x) = \bar{w}(x)$$

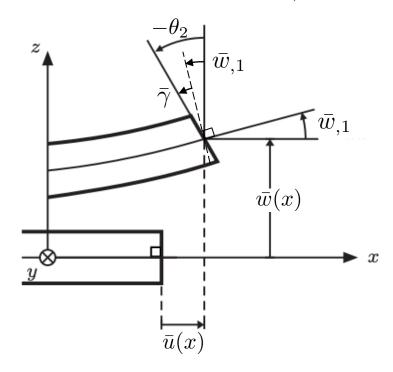
- Small-strain tensor, with $(\bar{w}_{,1})^2 \ll 1$

$$\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i})$$

$$\epsilon_{ij} = \begin{bmatrix} \bar{u}_{,1} + z\theta_{2,1} & 0 & (\theta_2 + \bar{w}_{,1})/2\\ 0 & 0 & 0\\ (\theta_2 + \bar{w}_{,1})/2 & 0 & 0 \end{bmatrix}$$

$$\epsilon_{ij} = \begin{bmatrix} \bar{\epsilon}_{11} + z\bar{\kappa}_{11} & 0 & \bar{\gamma}_{13}/2 \\ 0 & 0 & 0 \\ \bar{\gamma}_{13}/2 & 0 & 0 \end{bmatrix}$$

Simplified geometry: $b \ll L$, $h \ll L$



kinematic variables

 $\overline{\epsilon}_{11}$ $\overline{\kappa}_{11}$ $\overline{\gamma}_{13}$ extensional, bending, and shear components of beam strain

Aside: Euler-Bernoulli beams

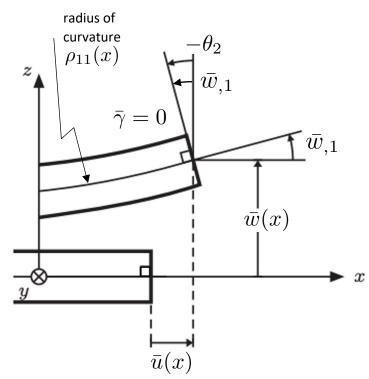
- Displacement field, with $\, heta_2 = - ar{w}_{,1}$

$$u_1(x, z) = \bar{u}(x) - z\bar{w}_{,1}(x)$$
$$u_2 = 0$$
$$u_3(x) = \bar{w}(x)$$

- Small-strain tensor, with $(\bar{w}_{,1})^2 \ll 1$

$$\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i})$$

$$\epsilon_{ij} = \begin{bmatrix} \bar{u}_{,1} - z\bar{w}_{,11} & 0 & 0\\ 0 & 0 & 0\\ 0 & 0 & 0 \end{bmatrix}$$



Simplified geometry: $b \ll L \;,\; h \ll L \;$ $\bar{w} \ll h \;$

$$\bar{\epsilon}_{11} = 0$$
 $\bar{w}_{,11} = \frac{1}{\rho_{11}} = -\kappa_{11} \implies \epsilon_{11} = -\frac{z}{\rho_{11}}$

Euler-Bernoulli kinematic assumption

Timoshenko beams

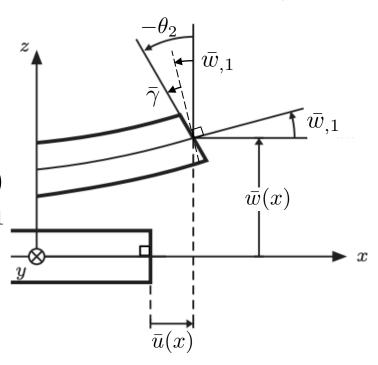
- Small-strain tensor

$$\epsilon_{ij} = \begin{bmatrix} \bar{\epsilon}_{11} + z\bar{\kappa}_{11} & 0 & \bar{\gamma}_{13}/2\\ 0 & 0 & 0\\ \bar{\gamma}_{13}/2 & 0 & 0 \end{bmatrix}$$

- Linear elasticity (generalized Hooke's law) assuming $\sigma_{22} \ll \sigma_{11}$ and $\sigma_{33} \ll \sigma_{11}$ Since lateral surfaces are traction free, stresses in 22 and 33 directions must be zero on free surfaces.

$$\sigma_{ij} = \begin{bmatrix} E(\bar{\epsilon}_{11} + z\bar{\kappa}_{11}) & 0 & \frac{E}{2(1+\nu)}\bar{\gamma}_{13} \\ 0 & 0 & 0 \\ \frac{E}{2(1+\nu)}\bar{\gamma}_{13} & 0 & 0 \end{bmatrix}$$

 Reconciled if the displacement field has higher order terms. Simplified geometry: $b \ll L$, $h \ll L$



solution of a mixed boundary condition problem

$$u_1(x, z) = \bar{u}(x) - z\bar{w}_{,1}(x) + \text{h.o.t}$$

 $u_2 = 0 + \text{h.o.t}$
 $u_3(x) = \bar{w}(x) + \text{h.o.t}$

Timoshenko beams

Small-strain tensor

$$\epsilon_{ij} = \begin{bmatrix} \bar{\epsilon}_{11} + z\bar{\kappa}_{11} & 0 & \bar{\gamma}_{13}/2 \\ 0 & 0 & 0 \\ \bar{\gamma}_{13}/2 & 0 & 0 \end{bmatrix}$$

$$\epsilon_{ij} = \begin{bmatrix} \bar{\epsilon}_{11} + z\bar{\kappa}_{11} & 0 & \bar{\gamma}_{13}/2 \\ 0 & 0 & 0 \\ \bar{\gamma}_{13}/2 & 0 & 0 \end{bmatrix} \qquad \sigma_{ij} = \begin{bmatrix} E(\bar{\epsilon}_{11} + z\bar{\kappa}_{11}) & 0 & \frac{E}{2(1+\nu)}\bar{\gamma}_{13} \\ 0 & 0 & 0 \\ \frac{E}{2(1+\nu)}\bar{\gamma}_{13} & 0 & 0 \end{bmatrix}$$

Linear elasticity (generalized Hooke's law) assuming $\sigma_{22} \ll \sigma_{11}$ and $\sigma_{33} \ll \sigma_{11}$ Since lateral surfaces are traction free, stresses in 22 and 33 directions must be zero on free surfaces.

incompatible with strain field

> Reissner's theory overcomes this issue

$$\begin{vmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{12} \end{vmatrix} = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} (1-\nu) & \nu & \nu & 0 & 0 & 0 \\ \nu & (1-\nu) & \nu & 0 & 0 & 0 \\ \nu & \nu & (1-\nu) & 0 & 0 & 0 \\ 0 & 0 & 0 & (1-2\nu)/2 & 0 & 0 \\ 0 & 0 & 0 & 0 & (1-2\nu)/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & (1-2\nu)/2 \end{bmatrix}$$

 ϵ_{22}

 ϵ_{33}

Timoshenko beams

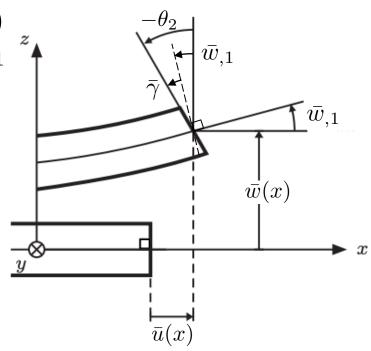
- Linear elasticity (generalized Hooke's law) assuming $\sigma_{22} \ll \sigma_{11}$ and $\sigma_{33} \ll \sigma_{11}$ Since lateral surfaces are traction free, stresses in 22 and 33 directions must be zero on free surfaces.

$$\sigma_{ij} = \begin{bmatrix} E(\bar{\epsilon}_{11} + z\bar{\kappa}_{11}) & 0 & \frac{E}{2(1+\nu)}\bar{\gamma}_{13} \\ 0 & 0 & 0 \\ \frac{E}{2(1+\nu)}\bar{\gamma}_{13} & 0 & 0 \end{bmatrix}$$

Internal resultants

$$N_{1} = \int_{A} \sigma_{11} dA \qquad M_{2} = \int_{A} z \sigma_{11} dA$$
$$V = K_{s} \int_{A} \sigma_{13} dA$$

Simplified geometry: $b \ll L$, $h \ll L$



beam geometry

height (h), width (b) cross-sectional area (A) moment of inertia (I) Shear correction factor (K_s)

Timoshenko beams

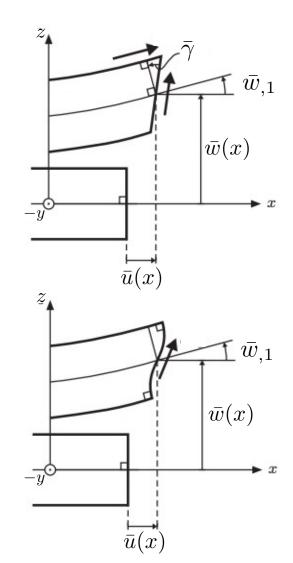
Internal resultants

$$N_{1} = b \int_{-h/2}^{h/2} E(\bar{\epsilon}_{11} + z\bar{\kappa}_{11}) dz = EA\bar{\epsilon}_{11}$$

$$M_{2} = b \int_{-h/2}^{h/2} E(z\bar{\epsilon}_{11} + z^{2}\bar{\kappa}_{11}) dz = EI_{22}\bar{\kappa}_{11}$$

$$V = K_{s}b \int_{-h/2}^{h/2} \frac{E}{2(1+\nu)} \bar{\gamma}_{13} dz = \frac{K_{s}AE}{2(1+\nu)} \bar{\gamma}_{13}$$

Note: The shear correction factor K_s is required in the formulation due to the absence of shear stress and strain at the top and bottom boundaries of the beam. K_s is computed such that resultant shear force V creates the same strain energy as does the true transverse stresses predicted by the three-dimensional elasticity theory.



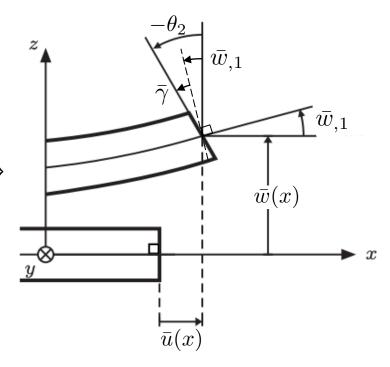
Timoshenko beams

Constitutive relation
 (relationship between internal resultants and kinematic variables)

$$\begin{cases} N_1 \\ M_2 \\ V \end{cases} = \begin{bmatrix} EA & 0 & 0 \\ 0 & EI_{22} & 0 \\ 0 & 0 & \frac{K_{\rm s}EA}{2(1+\nu)} \end{bmatrix} \begin{cases} \bar{\epsilon}_{11} \\ \bar{\kappa}_{11} \\ \bar{\gamma}_{13} \end{cases}$$

Euler-Bernoulli beams

- Constitutive relation



kinematic variables

 $\bar{\epsilon}_{11}(x)$ $\bar{\kappa}_{11}(x)$ $\bar{\gamma}_{13}(x)$ extensional, bending, and shear components of beam strain

Mindlin's plates

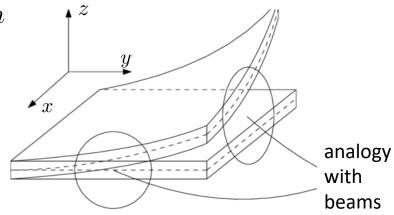
Simplified geometry: the plate is initially flat

- Kinematic assumptions, with $ar{w} \ll h$

$$u_1(x, y, z) = \bar{u}(x, y) + z\theta_1(x, y)$$

$$u_2(x, y, z) = \bar{v}(x, y) + z\theta_2(x, y)$$

$$u_3(x, y, z) = \bar{w}(x, y)$$



- Small-strain tensor, with $(\bar{w}_{,1})^2 \ll 1$

$$\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i})$$

$$\epsilon_{ij} = \begin{bmatrix} \bar{\epsilon}_{11} + z\bar{\kappa}_{11} & \bar{\gamma}_{12}/2 + z\bar{\kappa}_{12} & \bar{\gamma}_{13}/2 \\ \bar{\gamma}_{12}/2 + z\bar{\kappa}_{12} & \bar{\epsilon}_{22} + z\bar{\kappa}_{22} & \bar{\gamma}_{23}/2 \\ \bar{\gamma}_{13}/2 & \bar{\gamma}_{23}/2 & 0 \end{bmatrix}$$

kinematic variables

$$\bar{\epsilon}_{11}$$
 $\bar{\epsilon}_{22}$ $\bar{\kappa}_{11}$ $\bar{\kappa}_{22}$

extensional strains, bending strains

kinematic variables (cont.)

$$\bar{\gamma}_{12}$$
 $\bar{\kappa}_{12}$ $\bar{\gamma}_{13}$ $\bar{\gamma}_{23}$

contribution of the mid-plane displacement to in-plane shear, contribution of normal rotations to in-plane shear, and shear components

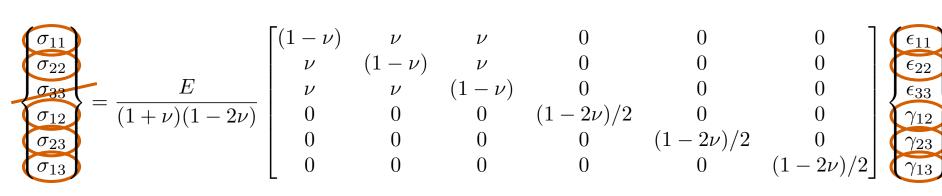
Mindlin's plates

- Small-strain tensor

$$\epsilon_{ij} = \begin{bmatrix} \bar{\epsilon}_{11} + z\bar{\kappa}_{11} & \bar{\gamma}_{12}/2 + z\bar{\kappa}_{12} & \bar{\gamma}_{13}/2 \\ \bar{\gamma}_{12}/2 + z\bar{\kappa}_{12} & \bar{\epsilon}_{22} + z\bar{\kappa}_{22} & \bar{\gamma}_{23}/2 \\ \bar{\gamma}_{13}/2 & \bar{\gamma}_{23}/2 & 0 \end{bmatrix}$$

- Linear elasticity (generalized Hooke's law) assuming $\sigma_{33} \ll \sigma_{22}$ and $\sigma_{33} \ll \sigma_{11}$ Since top/bottom surfaces are traction free, the stress in 33 direction must be zero on free surfaces.

solution of a mixed boundary condition problem



Kirchhoff plates

- Small-strain tensor, with $\, heta_2 = -ar w_{,1}\,\,,\,\, heta_1 = -ar w_{,2}\,$

$$\epsilon_{ij} = \begin{bmatrix} \bar{\epsilon}_{11} + z\bar{\kappa}_{11} & \bar{\gamma}_{12}/2 + z\bar{\kappa}_{12} & \bar{\gamma}_{13}/2 \\ \bar{\gamma}_{12}/2 + z\bar{\kappa}_{12} & \bar{\epsilon}_{22} + z\bar{\kappa}_{22} & \bar{\gamma}_{23}/2 \\ \bar{\gamma}_{13}/2 & \bar{\gamma}_{23}/2 & 0 \end{bmatrix}$$

- Linear elasticity (generalized Hooke's law) assuming $\sigma_{33} \ll \sigma_{22}$ and $\sigma_{33} \ll \sigma_{11}$ Since top/bottom surfaces are traction free, the stress in 33 direction must be zero on free surfaces.

solution of a mixed boundary condition problem

$$\begin{vmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{12} \end{vmatrix} = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} (1-\nu) & \nu & \nu & 0 & 0 & 0 \\ \nu & (1-\nu) & \nu & 0 & 0 & 0 \\ \nu & \nu & (1-\nu) & 0 & 0 & 0 \\ 0 & 0 & 0 & (1-2\nu)/2 & 0 & 0 \\ 0 & 0 & 0 & 0 & (1-2\nu)/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & (1-2\nu)/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & (1-2\nu)/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & (1-2\nu)/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & (1-2\nu)/2 \end{bmatrix} \begin{vmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ \gamma_{12} \\ \gamma_{13} \\ \gamma_{13} \end{vmatrix}$$

Mindlin's plates (next lecture ...)

- Internal resultants

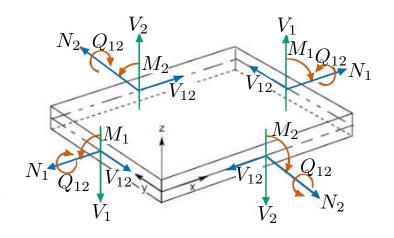
$$N_{1} = b \int_{-h/2}^{h/2} E(\bar{\epsilon}_{11} + z\bar{\kappa}_{11}) dz = EA\bar{\epsilon}_{11}$$

$$N_{2} Q_{12}$$

$$M_{2} = b \int_{-h/2}^{h/2} E(z\bar{\epsilon}_{11} + z^{2}\bar{\kappa}_{11}) dz = EI_{22}\bar{\kappa}_{11}$$

$$V = K_{s}b \int_{-h/2}^{h/2} \frac{E}{2(1+\nu)} \bar{\gamma}_{13} dz = \frac{K_{s}AE}{2(1+\nu)} \bar{\gamma}_{13}$$

$$N_{1} Q_{12} V_{12}$$



... and more!!!

- Constitutive relation

(relationship between internal resultants and kinematic variables)

kinematic variables

$$ar{\epsilon}_{11}$$
 $ar{\epsilon}_{22}$ $ar{\kappa}_{11}$ $ar{\kappa}_{22}$ extensional strains, bending strains

kinematic variables (cont.)

$$\bar{\gamma}_{12}$$
 $\bar{\kappa}_{12}$ $\bar{\gamma}_{13}$ $\bar{\gamma}_{23}$ contribution of the mid-plane displa

contribution of the mid-plane displacement to in-plane shear, contribution of normal rotations to in-plane shear, and shear components

Any questions?