Regression #2

Econ 671

Purdue University

- In this lecture, we address estimation of the linear regression model.
- There are many objective functions that can be employed to obtain an estimator; here we discuss the most common one that delivers the familiar *OLS estimator*.
- We then discuss issues of parameter interpretation, prediction and review details associated with *R*-squared.

Estimation

$$y_i = x_i\beta + \epsilon_i.$$

The most widely employed approach seeks to minimize the contribution of the error term ϵ_i by minimizing the sum of squared residuals:

$$\min_{\tilde{\beta}}\sum_{i}(y_{i}-x_{i}\tilde{\beta})^{2}=\min_{\tilde{\beta}_{1},\tilde{\beta}_{2},...,\tilde{\beta}_{k}}\sum_{i}(y_{i}-\tilde{\beta}_{1}-\tilde{\beta}_{2}x_{i2}-\cdots-\tilde{\beta}_{k}x_{ik})^{2}.$$

Unlike the simple regression case, where we consider k = 2 specifically, and derive an estimator for that particular case, we seek to obtain an estimator when k is an arbitrary number.

A "representative" first-order condition from this objective function (differentiating with respect to $\tilde{\beta}_j$) yields an equation of the form:

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This implies that, for the intercept parameter:

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The complete vector $\hat{\beta}$ is obtained as the solution of this set of k equations in k unknowns.

Estimation

We can assemble these k equations together in vector / matrix form as:

 $\begin{bmatrix} x_{11} & x_{21} & \cdots & x_{n1} \\ x_{12} & x_{22} & \cdots & x_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ x_{1k} & x_{2k} & \cdots & x_{nk} \end{bmatrix} \begin{pmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} - \begin{bmatrix} x_{11} & x_{12} & \cdots & x_{1k} \\ x_{21} & x_{22} & \cdots & x_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \cdots & x_{nk} \end{bmatrix} \begin{bmatrix} \hat{\beta}_1 \\ \hat{\beta}_2 \\ \vdots \\ \hat{\beta}_k \end{bmatrix} \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$

or, compactly in terms of our regression notation,

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Under the assumptions of our regression model, then,

Estimation

Of course, arriving at $\hat{\beta} = (X'X)^{-1}X'y$ is easier and more direct if we simply apply rules governing vector differentiation. (See, Appendix A). That is, we seek to minimize:

$$\min_{ ilde{eta}}(y-X ilde{eta})'(y-X ilde{eta})$$

or

$$\min_{\tilde{eta}}\left(y'y-\tilde{eta}'X'y-y'X\tilde{eta}+\tilde{eta}'X'X\tilde{eta}
ight).$$

Differentiating with respect to the vector $\tilde{\beta}$ and setting the result to zero gives:

$$-2X'y+2X'X\hat{\beta}=0$$

or

$$\hat{\beta} = (X'X)^{-1}X'y.$$

- Thus we have a simple-to-calculate, closed form solution for the estimated coefficient vector.
- Given this estimated coefficient vector, fitted (predicted) values are easily obtained:

$$\hat{y} = X\hat{\beta}$$

• as are the residuals:

$$\hat{\epsilon} = y - X\hat{\beta}.$$

- As you all know, multiple regression is advantageous in that it allows the researcher to "control" for other factors when determining the effect of a particular x_j on y.
- Indeed, the language "After controlling for the influence of other factors, the marginal effect of x_i on y is $\hat{\beta}_i$ " is commonly used.
- In the following subsection, we justify this interpretation in a more formal way.

Consider the regression model:

$$y = X_1\beta_1 + x_2\beta_2 + \epsilon.$$

- Here, X_1 represents a set of covariates that are important to account for, but are not necessarily the objects of interest.
- x₂ is regarded as a vector (for simplicity and without loss of generality), so that β₁ is a (k − 1) × 1 vector while β₂ is a scalar.
- Some questions: How can we get $\hat{\beta}_2$ directly? Does this provide any insight behind the interpretation of multiple regression coefficients?

Interpretation

$$y = X_1\beta_1 + x_2\beta_2 + \epsilon.$$

We can write this as

$$y = \begin{bmatrix} X_1 & x_2 \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} + \epsilon.$$

To calculate

$$\hat{\beta} = (X'X)^{-1}X'y,$$

we then note that

$$X'X = \left[\begin{array}{cc} X_1' \\ x_2' \end{array}\right] \left[X_1 \quad x_2 \right] = \left[\begin{array}{cc} X_1'X_1 & X_1'x_2 \\ x_2'X_1 & x_2'x_2 \end{array}\right].$$

$$y = X_1\beta_1 + x_2\beta_2 + \epsilon.$$

Likewise,

$$X'y = \left[\begin{array}{c} X_1'\\ x_2' \end{array}\right]y = \left[\begin{array}{c} X_1'y\\ x_2'y \end{array}\right]$$

Putting these two equations together, we then obtain:

$$\begin{bmatrix} X_1'X_1 & X_1'x_2 \\ x_2'X_1 & x_2'x_2 \end{bmatrix} \begin{bmatrix} \hat{\beta}_1 \\ \hat{\beta}_2 \end{bmatrix} = \begin{bmatrix} X_1'y \\ x_2'y \end{bmatrix}$$

This produces two "equations:" the first, a vector-valued equation for $\hat{\beta}_1$ and the second a scalar equation for $\hat{\beta}_2$.

The first of these equations gives:

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We can rearrange this to get:

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The second of these equations also gives:

The last slide gave two equations in two unknowns. We can substitute the first of these into the second to get an expression that only involves $\hat{\beta}_2$:

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Regrouping terms gives:

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Let us define

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so that

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This provides a "direct" way to estimate the *short regression* coefficient β_2 .

The matrix M_1 has some nice properties:

• *M*₁ is *symmetric*:

• *M*₁ is *idempotent*:

With this in mind, we provide an alternate way to obtain $\hat{\beta}_2$ which helps to clarify its interpretation:

Theorem

 \hat{eta}_2 can be obtained from the following two-step procedure:

Proof.

The proof of this result is straightforward. To see this, consider the regression in step 1:

$$x_2 = X_1\theta + u$$

The estimated residuals are obtained as:

Proof.

In the second step, we fit the regression:

$$y = \gamma \hat{u} + \eta.$$

Therefore,

- So, $\hat{\beta}_2$ can be obtained from this two-step procedure.
- The procedure is rather intuitive: The way that we estimate β₂ is to first find the part of x₂ that cannot be (linearly) explained by X₁. (These are the residuals, û). We then regress y on this "leftover" part of x₂ to get β₂.
- This procedure is often referred to as *residual regression*. It also clearly justifies our common interpretation of the coefficient as "after controlling for the effect of X₁."

- Undoubtedly, most (all?) of you are familiar with the coefficient of determination or R².
- *R*² is often a useful diagnostic, measuring the proportion of variation in the data that is explainable by variation among the explanatory variables in the model.
- In what follows, we briefly review its derivation and discuss some of its properties.

To begin, define the *total sum of squares (TSS)* as follows:

Likewise, we can define the *explained sum of squares (ESS)* as follows:

and, again, in vector / matrix form, this can be written as:

and the *residual sum of squares*:

We now introduce two results, both rather obvious, but will be needed when constructing R^2 :

 $\iota'\hat{\epsilon}=0$

Proof.

Our second result states:

$$(\hat{y}-\iota \overline{y})'\,\hat{\epsilon}=0.$$

Proof.

The second line follows from the result we have just proved. The last line again follows from the fact that $X'\hat{\epsilon} = 0$, by construction of the OLS estimator.

With these result in hand, we can now derive R^2 . To this end, note:

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which implies

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Since this holds for each element of the above vectors, the sum of squared elements must also be equal:

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Using our previous result, the right hand side reduces to:

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or

The coefficient of determination, R^2 is then defined as:

$$R^2 = \frac{ESS}{TSS}$$
 or $R^2 = 1 - \frac{RSS}{TSS}$.

Some properties:

