

BYUNG-CHEOL MIN

Assistant Professor, Purdue University

CONTACT INFORMATION

Computer and Information Technology
Purdue Polytechnic Institute
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RESEARCH INTERESTS

Control of multi-robot systems; Human-robot interaction in assistive robotics; Design and development of robotic sensor networks; Evolutionary algorithms for autonomous system control; Artificial intelligence in multi-agent systems and cyber-physical systems.

Applications of my research include field robotics, assistive technology, search-and-rescue robots, networked robotics, unmanned aerial/surface/underwater vehicles, robot navigation, object tracking, formation control, and embedded systems.

EDUCATION

- Post-Doc, The Robotics Institute** June 2014 – July 2015
Carnegie Mellon University, Pittsburgh, PA, USA
Advisors: Prof. M. Bernardine Dias and Prof. Aaron Steinfeld
- Ph.D., Technology** (Specialization: Computer and Information Technology) May 2014
Purdue University, West Lafayette, IN, USA
Dissertation: Optimizing Self-organizing, Large-scale, Mobile Robotic Broadband Networks
Advisor: Prof. Eric Matson
- M.S., Electronics and Radio Engineering** Aug 2010
Kyung Hee University, Yongin, Korea
Thesis: Navigation Method for VTOL Type UAV using a Limit-cycle Navigation Method and Fuzzy Logic Control
Advisor: Prof. Donghan Kim
- B.S., Electronics Engineering** Aug 2008
Kyung Hee University, Yongin, Korea
Thesis: Humanoid Robot with Webcam

PROFESSIONAL EXPERIENCE

- Assistant Professor** Aug 2015 – Present
Department of Computer and Information Technology, Purdue Polytechnic Institute, Purdue University, West Lafayette, IN
- Postdoctoral Researcher** June 2014 – July 2015
TechBridgeWorld Research Group, Field Robotics Center, The Robotics Institute, Carnegie Mellon University, Pittsburgh, PA
- Sergeant** July 2001 – Sept 2003
Air Operations Command, Republic of Korea Army (ROKA), Icheon, Korea

HONORS AND AWARDS

- **Summer Faculty Research Fellowship**, Purdue Research Foundation (PRF) Summer Faculty Research Fellowship, Purdue University 2017
- **Polytechnic Post-Doc Support Competition Award**, Purdue University 2016

- **Best Paper Award** at the 28th ICROS (Institute of Control, Robotics and Systems) Annual Conference, for the paper: “A Dust Detection Sensor System for Improvement of a Robot Vacuum Cleaner” 2013
- **Research Scholarship** awarded to the student for top research accomplishment by Kyung Hee University 2009, 2010
- **3rd Place Award** at the International Robot Contest 2009 (IRC2009), participated in: FIRA Challenge Cup Robot Soccer Competition 2009
- **Best Paper Award** at the Proceedings of KIIS (Korean Institute of Intelligent System) Spring Conference 2009, for the paper: “Development of Violin Self-Training using Fuzzy Logic” 2009
- **4th Place Award** at the International Robot Contest 2008 (IRC2008), participated in: “FIRA Challenge Cup Robot Soccer Competition” 2008
- **The Gold Lion Prize** awarded for the top volunteer student; 232 total hours of volunteer service during 2006–2008, by Kyung Hee University 2008
- **Best Thesis Award** in Graduation Thesis Competition in the Fall of 2007 at Kyung Hee University, for the thesis: “Humanoid Robot with Webcam” 2008
- **Useful Idea Award** in the Contest for the 3rd Rehabilitation Assistive Devices, by Korean Ministry of Health and Welfare, for the idea: “Design of Electro Oculogram (EOG) Control for a Motorized Wheelchair” 2007
- **Academic Scholarship** awarded to the student for outstanding GPA by Kyung Hee University 2004, 2006, 2007

PUBLICATIONS

Journal Publications

- [1] Jonghoek Kim, Ramvijas Parasuraman, Shaocheng Luo, and Byung-Cheol Min, “Multi-Point Rendezvous in Multi-Robot Systems”, *IEEE Transactins on Cybernetics*. (Under review)
- [2] Byung-Cheol Min, Ramvijas Parasuraman, Sangjun Lee, Jin-Woo Jung, and Eric T. Matson, “A Directional Antenna based Leader-Follower Relay System for End-to-End Robot Communications”, *Robotics and Autonomous Systems*, Available online December 2017.
- [3] Daniel K. Schrader, Byung-Cheol Min, Eric T. Matson, and J. Eric Dietz, “Real-time averaging of position data from multiple GPS receivers”, *Measurement*, Vol. 90, pp. 329-337, August 2016.
- [4] Byung-Cheol Min, Yongho Kim, Sangjun Lee, Jin-Woo Jung, and Eric T. Matson “Finding the Optimal Location and Allocation of Relay Robots for Building a Rapid End-to-end Wireless Communication”, *Ad Hoc Networks*, Vol. 39, Issue 15, pp. 23-44, March 2016.
- [5] Byung-Cheol Min, Eric T. Matson, and Jin-Woo Jung, “Active Antenna Tracking System with Directional Antennas for Enhancing Wireless Communication Capabilities of a Networked Robotic System”, *Journal of Field Robotics*, 2015.
- [6] Byung-Cheol Min, Eric T. Matson, Jinung An, and Donghan Kim, “Improvement of Violinist Robot using a Passive Damper Device”, *Journal of Intelligent and Robotic Systems*, Vol. 72, Issue 3-4, pp. 343-355, Dec. 2013.
- [7] Byung-Cheol Min, John Lewis, Eric T. Matson, and Anthony H. Smith, “Heuristic Optimization Techniques for Self-orientation of Antennas in Long-distance Point-to-point Broadband Networks”, *Ad Hoc Networks*, Vol. 11, Issue 8, pp. 2252-2263, Nov. 2013.
- [8] John Lewis, Eric T. Matson, Sherry Wei, and Byung-Cheol Min, “Implementing HARMS-based Indistinguishability in Ubiquitous Robot Organizations”, *Robotics and Autonomous Systems*, Vol. 61, No. 11, pp. 1186-1192, Nov. 2013.
- [9] Dong-Hoe Kim, Byung-Cheol Min, and Donghan Kim, “A Dust Detection Sensor System for Improvement of a Robot Vacuum Cleaner”, *Journal of Institute of Control, Robotics and Systems*, Oct. 2013.
- [10] Cory Q. Nguyen, Byung-Cheol Min, Eric T. Matson, Anthony H. Smith, J. Eric Dietz, and Donghan Kim, “Using Mobile Robots to Establish Mobile Wireless Mesh Networks and Increase Network Throughput”, *International Journal of Distributed Sensor Networks*, Vol. 2012, Article ID 614532, 2012.

- [11] Byung-Cheol Min, Moon-Su Kim, and Donghan Kim, "Fuzzy Logic Path Planner and Motion Controller by Evolutionary Programming for Mobile Robots", *International Journal of Fuzzy Systems*, Vol. 11, No. 3, pp. 154-163, Sep. 2009.
- [12] Byung-Cheol Min, Donghan Kim, Yoon Hyuk Kim, Ki Yeoul Kim, and Chongkug Park, "Development of Violin Self-Training Algorithm Using Fuzzy Logic", *Journal of Korean Institute of Intelligent Systems*, Vol. 19, No. 4, Aug. 2009.

Book Chapters (Refereed)

- [1] Soo Hyeok Kang, Yong Ho Kim, Byung-Cheol Min, Soon-Geul Lee, Jinung An, Donghan Kim, "Smart Floor with Learning Capability for Mobile Robot System", *Recent Advances in Robotics and Automation (Series: Studies in Computational Intelligence)*, Vol. 480, pp. 205-215, Springer Berlin Heidelberg, 2013.

Conference Proceedings (Refereed)

- [1] Ramvijas Parasuraman and Byung-Cheol Min, "A Weighted Bearing Consensus Controller for Coordinate-free Multi-Robot Rendezvous using Direction of Arrival of Wireless Signals", *Robotics and Automation (ICRA), 2018 IEEE International Conference on*, Brisbane, Australia, May 21-25, 2018. (Under review)
- [2] Sangjun Lee, Yongbum Cho, and Byung-Cheol Min, "Direction of Arrival Estimation-aided Cyberattack Detection in Networked Multi-Robot Systems", *Robotics and Automation (ICRA), 2018 IEEE International Conference on*, Brisbane, Australia, May 21-25, 2018. (Under review)
- [3] Tamzidul Mina and Byung-Cheol Min, "Penguin Huddling-inspired Energy Sharing and Formation Movement in Multi-robot Systems", *Robotics and Automation (ICRA), 2018 IEEE International Conference on*, Brisbane, Australia, May 21-25, 2018. (Under review)
- [4] Sangjun Lee, Yongbum Cho, and Byung-Cheol Min, "Attack-aware Multi-sensor Integration Algorithm for Autonomous Vehicle Navigation Systems", *2017 IEEE International Conference on Systems, Man and Cybernetics (SMC)*, Banff, Canada, 5-8 October, 2017.
- [5] Yeonju Oh, Wei-Liang Kao, and Byung-Cheol Min, "Indoor Navigation Aid System Using No Positioning Technique for Visually Impaired People", *HCI International 2017*, Poster Extended Abstract, Vancouver, Canada, 9-14 July, 2017.
- [6] Manoj Penmetcha, Arabinda Samantaray, and Byung-Cheol Min, "SmartResponse: Emergency and Non-Emergency Response for Smartphone based Indoor Localization applications", *HCI International 2017*, Poster Extended Abstract, Vancouver, Canada, 9-14 July, 2017.
- [7] Hyun Hwang, Jun Han Bae, and Byung-Cheol Min, "Design Guidelines for Sensor Locations on 3D Printed Prosthetic Hands", *IEEE Robotic Computing (IRC) 2017*, Taichung, Taiwan, April 10-12, 2017.
- [8] Sangmi Shin, Byung-Cheol Min, Julia Rayz, and Eric T. Matson, "Semantic Knowledge-based Language Education Device for Children with Developmental Disabilities", *IEEE Robotic Computing (IRC) 2017*, Taichung, Taiwan, April 10-12, 2017.
- [9] Huanhuan Wang, Pai-Ying Hsiao, and Byung-Cheol Min, "Examine the Potential of Robots to Teach Autistic Children Emotional Concepts: A Preliminary Study", *The Eight International Conference on Social Robotics (ICSR)*, Kansas City, USA, Nov. 1-3, 2016.
- [10] Jun Han Bae, Jeehwan Park, Sangjun Lee, and Byung-Cheol Min, "Tri-SedimentBot: An Underwater Sediment Sampling Robot", *Automation Science and Engineering (CASE), 2016 IEEE International Conference on*, Fort Worth, Texas, USA, Aug. 21-24, 2016.
- [11] Kangwei Chen, Victoria Plaza-Leiva, Byung-Cheol Min, Aaron Steinfeld, and M. Bernardine Dias, "NavCue: Context Immersive Navigation Assistance for Blind Travelers", *11th ACM/IEEE International Conference on Human-Robot Interaction (HRI) Videos*, 2016.
- [12] Byung-Cheol Min, Suryansh Saxena, Aaron Steinfeld, and M. Bernardine Dias, "Incorporating Information from Trusted Sources to Enhance Urban Navigation for Blind Travelers", *IEEE International Conference on Robotics and Automation (ICRA)*, Seattle, Washington, May 26-30, 2015.

- [13] Byung-Cheol Min, Aaron Steinfeld, and M. Bernardine Dias, "How Would You Describe Assistive Robots to People Who are Blind or Low Vision?", *Proceedings of the Tenth Annual ACM/IEEE International Conference on Human-Robot Interaction (HRI) Extended Abstracts*, 2015.
- [14] Byung-Cheol Min, Eric T. Matson, Anthony H. Smith, and J. Eric Dietz, "Using Directional Antennas as Sensors to Assist Fire-fighting Robots in Large Scale Fires", *2014 IEEE Sensors Applications Symposium (SAS)*, Queenstown, New Zealand, Feb. 18-20, 2014.
- [15] Byung-Cheol Min and Eric T. Matson, "Robotic Follower System using Bearing-only Tracking with Directional Antennas", in *Proc. International Conference on Robot Intelligence Technology and Applications (RiTA)*, pp. 37-58, 2014.
- [16] Esther Rolf, Matt Whitlock, Byung-Cheol Min, and Eric T. Matson, "Enhancing Wi-Fi Signal Strength of a Dynamic Heterogeneous System Using a Mobile Robot Provider", in *Proc. International Conference on Robot Intelligence Technology and Applications (RiTA)*, pp. 927-937, 2014.
- [17] Jae-Seok Yoon, Byung-Cheol Min, Seong-Og Shin, and Donghan Kim, "GA-based Optimal Waypoint Design for Improved Path Following of Mobile Robot", in *Proc. International Conference on Robot Intelligence Technology and Applications (RiTA)*, pp. 127-136, 2014.
- [18] Byung-Cheol Min, Eric T. Matson, and Bakytgul Khaday, "Design of a Networked Robotic System Capable of Enhancing Wireless Communication Capabilities", *11th IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR)*, Sweden, Oct. 21-26, 2013.
- [19] Sangyup Lee, Byung-Cheol Min, Dong-Hoe Kim, Jae-Seok Yoon, and Donghan Kim, "Passive RFID Positioning System Using RF Power Control", in *Proc. International Conference on Robot Intelligence Technology and Applications (RiTA)*, Gwangju, Korea, Dec. 2012.
- [20] Ji Hyeon Hong, Byung-Cheol Min, Julia M. Taylor, Victor Raskin, and Eric T. Matson, "NL-Based Communication with Firefighting Robots", *2012 IEEE International Conference on Systems, Man, and Cybernetics (SMC)*, pp. 1461-1466, Seoul, Korea, Oct. 14-17, 2012.
- [21] Soo Hyeok Kang, Byung-Cheol Min, Ji Hyeon Hong, Eric T. Matson, Soon-Geul Lee, and Donghan Kim, "Novel Positioning System for Mobile Robot Using RFID Power Control", *Joint Proceedings of the 13th Annual TAROS Conference and the 15th Annual FIRA RoboWorld Congress*, Bristol, UK, August 20-23, 2012.
- [22] Daniel K. Schrader, Byung-Cheol Min, Eric T. Matson, and J. Eric Dietz, "Combining Multiple, Inexpensive Receivers to Improve Accuracy and Reliability", *2012 IEEE Sensors Applications Symposium (SAS)*, University of Brescia, Italy, Feb. 7-9, 2012.
- [23] Byung-Cheol Min, John Lewis, Daniel K. Schrader, Eric T. Matson, and Anthony H. Smith, "Self-orientation of Antennas, Assisted by Mobile Robots, for Receiving the Best Wireless Signal", *2012 IEEE Sensors Applications Symposium (SAS)*, University of Brescia, Italy, Feb. 7-9, 2012.
- [24] Eric T. Matson, Julia M. Taylor, Victor Raskin, Byung-Cheol Min, and E. Cho Wilson, "A Natural Language Exchange Model for Enabling Human, Agent, Robot and Machine Interaction", *5th International Conference on Automation, Robotics and Applications (ICARA)*, Wellington, New Zealand, Dec. 6-8, 2011.
- [25] Soo Hyeok Kang, Yong Ho Kim, Eun Jin Lee, Soon-Geul Lee, Byung-Cheol Min, Jinung An, and Donghan Kim, "Implementation of Smart Floor for Multi-Robot System", *5th International Conference on Automation, Robotics and Applications (ICARA)*, Wellington, New Zealand, Dec. 6-8, 2011.
- [26] Byung-Cheol Min, Ji Hyeon Hong, and Eric T. Matson, "Adaptive Robust Control (ARC) for an Altitude Control of a Quadrotor Type UAV Carrying an Unknown Payloads", *2011 11th International Conference on Control, Automation and Systems (ICCAS)*, KINTEX, Gyeonggi-do, Korea, Oct. 26-29, 2011.
- [27] Eric T. Matson and Byung-Cheol Min, "M2M infrastructure to integrate humans, agents and robots into collectives", *Instrumentation and Measurement Technology Conference (I2MTC)*, 2011 IEEE, Hangzhou, China, May 10-12, 2011.
- [28] Byung-Cheol Min, Hina Chaudhry, Eric T. Matson, Anthony H. Smith, and J. Eric Dietz, "Rural Energy Security using Autonomous Micro-turbine Smart Grids", *2011 IEEE Rural Power Conference (IEEE REPC)*, Chattanooga, Tennessee, USA, April 10-13, 2011.

- [29] Jeong Wan Kim, Yong Ho Kim, Byung-Cheol Min, and Donghan Kim, "Tacit Navigation Method for Multi-Agent System", in *Proc. FIRA Robot World Congress*, Bangalore, India, Sep. 15-17, 2010.
- [30] Byung-Cheol Min, Hee Yeul Kwon, and Donghan Kim, "Path Planning Algorithm for VTOL Type UAVs Based on the Methods of Ray Tracing and Limit Cycle", *IEEE International Symposium on Computational Intelligence in Robotics and Automation (CIRA)*, Dajeon, Korea, Dec. 2009.
- [31] Byung-Cheol Min, Chan Ho Cho, Kyung Min Choi, and Donghan Kim, "Development of a Micro Quad-Rotor UAV for Monitoring an Indoor Environment", in *Proc. FIRA Robot World Congress*, Incheon, Korea, Aug. 16-20, 2009.
- [32] Chan Ho Cho, Byung-Cheol Min, and Donghan Kim, "A Gait Generation for an Unlocked Joint Failure of the Quadruped Robot with Balance Weight", in *Proc. FIRA Robot World Congress*, Incheon, Korea, Aug. 16-20, 2009.
- [33] Byung-Cheol Min, Eun Jin Lee, Soo Hyeok Kang, and Donghan Kim, "Limit-cycle Navigation Method for a Quad-rotor Type UAV", *Industrial Electronics, 2009. ISIE 2009, IEEE International Symposium on*, pp. 1352-1357, Seoul, Korea, July 2009.

Reports & Abstracts

- [1] Ramvijas Parasuraman, Sergio Caccamo, Luigi Freda, Petter Ögren, and Byung-Cheol Min, "An Approach to Retrieve from Communication Loss in Field Robots", *Robotics: Science and Systems (RSS) 2017, Workshop on Robot Communication in the Wild: Meeting the Challenges of Real-World Systems*, MIT, Massachusetts, USA, July 12-16, 2017.
- [2] Danilo Tardioli, Ramvijas Parasuraman, Petter Ögren, and Byung-Cheol Min, "Pound: A ROS Node to Improve Communication Latency Performance in Multi-Robot Systems", *Robotics: Science and Systems (RSS) 2017, Workshop on Robot Communication in the Wild: Meeting the Challenges of Real-World Systems*, MIT, Massachusetts, USA, July 12-16, 2017.
- [3] M. Bernardine Dias, Ermine Teves, Eric Hochendoner, Praneetha Sistla, Byung-Cheol Min, and Aaron Steinfeld, "Enhancing the Safety of Visually Impaired Travellers in and around Transit Stations", *The U.S. Department of Transportation, University Transportation Centers Program*, 2016.
- [4] Jun Han Bae, Dong Hun Lee, and Byung-Cheol Min, "Design and Concept of the Sediment Sampling Robot and Dynamic Buoy", *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2016)*, Late-Breaking Reports, Daejeon, Korea, Oct. 9-14, 2016.
- [5] Jun Han Bae, Eric T. Matson, and Byung-Cheol Min, "Towards an Autonomous Water Monitoring System with an Unmanned Aerial and Surface Vehicle Team", *2015 IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR)*, West Lafayette, IN, USA, Oct. 18-20, 2015.
- [6] Byung-Cheol Min, Aaron Steinfeld, and M. Bernardine Dias, "Towards Effective Human-Robot Interaction for Visually Impaired Adults", *ICRA 2015, Late-Breaking Reports*, Seattle, May 26-30, 2015.
- [7] Alekhya Jonnalagedda, Lucy Pei, Suryansh Saxena, Ming Wu, Byung-Cheol Min, Ermine A. Teves, Aaron Steinfeld, and M. Bernardine Dias, "Enhancing the Safety of Visually Impaired Travelers in and around Transit Stations", tech. report CMU-RI-TR-14-28, Robotics Institute, Carnegie Mellon University, December, 2014.

Patents

- [1] Byung-Cheol Min et al., "Method for providing guidance information based on user information", Patent No. 1011983850000, October 2012. (Korean Patent)
- [2] Byung-Cheol Min et al., "Apparatus for Cleaning Exterior Wall of Building", Patent No. 1011815400000, September 2012. (Korean Patent)
- [3] Byung-Cheol Min et al., "Walking guide Robot for blind person", Patent No. 1011468550000, May 2012. (Korean Patent)
- [4] Byung-Cheol Min et al., "LED Lighting Apparatus with Air Levitation System", Patent No. 1010905640000, November 2011. (Korean Patent)

- [5] Byung-Cheol Min et al., “Embedding Device for RFID Tag”, Patent No. 101056 8640000, August 2011.
(Korean Patent)

GRANTS

External Research Grants

Awarded

- Cybersecurity and Safety Challenges in Autonomous Vehicles: Threats Identification and Countermeasures Development, Role: PI, Sponsor: National Institute of Justice, Amount: **\$50,000** (08/01/2017 – 07/31/2018).
- Workshop to Explore US/Korean Collaboration in Human-Friendly Co-Robotic Technologies, Role: Co-PI (PI: Richard Voyles), Sponsor: National Science Foundation, Amount: **\$14,980** (09/01/2017 – 08/31/2018).
- I/UCRC Phase I: Robots and Sensors for the Human Well-being, Role: Senior Personnel (PI: Richard Voyles), Sponsor: National Science Foundation, Amount: **\$364,100** (09/15/2014 – 08/31/2020).
- Sejong-Purdue Program 2016, Role: Co-PI (PI: Eric T. Matson), Sponsor: Sejong University, Korea, Amount: **\$89,998** (05/01/2016 – 12/31/2016).
- KyungPook National-IITP-Purdue Summer Software Program, Role: Co-PI (PI: Eric T. Matson), Sponsor: Kyungpook National University, Korea, Amount: **\$45,426** (05/01/2016 – 12/31/2016).

In Review

- UNSA NEXUS: Robotic Water Quality Monitoring and Distribution Systems: A Pilot Study, Role: PI, Sponsor: Universidad Nacional de San Agustin, Amount: **\$365,439** (01/01/2018 – 12/31/2019).
- Collaborative Robotic Lift Assist for Improved Operator Compatibility Role: Co-PI (PI: Richard Voyles), Sponsor: Fiat Chrysler Automobiles, Amount: **\$381,731** (01/01/2018 – 06/30/2019).
- Towards Autonomous Robotic Systems for Harmful Algae Blooms (HABs) Control: Development of Robotic Platforms Role: PI, Sponsor: Indiana Water Resources Research Center, Amount: **\$15,000** (03/01/2018 – 02/28/2019).
- Towards Autonomous Robotic Systems for Harmful Algae Blooms (HABs) Control: Development of Perception Systems Role: PI, Sponsor: Ralph W. and Grace M. Showalter Research Trust, Amount: **\$75,000** (07/01/2018 – 06/30/2019).
- Multi-point Rendezvous Control in Networked Multi-Robot Systems Role: PI, Sponsor: Amazon.com, Amount: **\$63,636** (01/01/2018 – 12/31/2018).
- Cloud-based Robotic Water Monitoring Systems Role: PI, Sponsor: Amazon.com, Amount: **\$61,636** (01/01/2018 – 12/31/2018).
- CPS: Medium: Collaborative Research: Close Loop Sustainable Precision Animal Agriculture Role: Co-PI (PI: Richard Voyles), Sponsor: National Science Foundation, Amount: **\$579,703** (08/14/2017 – 08/13/2020).

Internal Research Grants

Awarded

- Purdue Research Foundation (PRF) Summer Faculty Research Grant, Role: PI, Sponsor: Purdue University, Amount: **\$8,000** (06/01/2017 – 07/31/2017).
- Provost Major Equipment Grant: Bi-Manual Dexterous Manipulation for Intuitive Autonomy, Role: Co-PI (PI: Richard Voyles), Sponsor: Purdue University, Amount: **\$144,732** (07/01/2016 – 06/31/2017).
- Polytechnic Post-Doc Support Competition Award, Role: PI, Sponsor: Purdue University, Amount: **\$100,000** (10/01/2016 – 09/31/2018)

In Review

- 17-18 Laboratory & University Core Facility Research Equipment Program, Role: PI, Sponsor: Purdue University, Amount: **\$89,200** (01/01/2018 – 12/31/2018).
- Catalyzing Large-scale Human Cooperation for Disaster Response, Role: Co-PI(PI: David Yu), Sponsor: Purdue University, Amount: **\$20,000** (07/01/2018 – 06/31/2019).

SEMINARS, INVITED TALKS & PRESENTATIONS

- | | |
|---|---------------|
| [1] Keynote speech at the 2016 International Workshop on ICT in Medicine and Health Care (ICTMHC 2016), Yeongnam Univ., Korea | June 2016 |
| [2] DGIST, Daegu, Korea | June, 2016 |
| [3] Chungnam National University, Daejeon, Korea | June, 2016 |
| [4] Dongguk University, Seoul, Korea | May, 2016 |
| [5] Kyung Hee University, Yongin, Korea | May, 2016 |
| [6] Indiana University-Purdue University Indianapolis (IUPUI), Indianapolis, IN USA | January, 2016 |
| [7] Purdue University, Robotics Seminar Series, West Lafayette, IN USA | January, 2016 |
| [8] Kyung Hee University, Yongin, Korea | October, 2015 |
| [9] Gacheon University, Seongnam, Korea | April, 2015 |
| [10] Dongguk University, Seoul, Korea | April, 2015 |
| [11] Korea Institute of Science and Technology (KIST), Seoul, Korea | April, 2015 |
| [12] Transportation Research Board 94th Annual Meeting, Washington D.C., USA | January, 2015 |

COURSES TAUGHT

Undergraduate Courses

- Software Development for Mobile Devices II (CNIT 425, Course Eval: 4.9/5.0 Student#: 11), Purdue Univ. Spring 2017
- Software Development for Mobile Computers (CNIT 355, Course Eval: 4.6/5.0, Student#: 22), Purdue Univ. Fall 2016

Graduate Courses

- Software Design and Development for Robotics (CNIT 581-SDR, Course Eval: –/–, Student#: 8), Purdue Univ. Spring 2017
- Software Design and Development for Robotics (CNIT 581-SDR, Course Eval: 5.0/5.0, Student#: 11), Purdue Univ. Spring 2016
- Introduction to Assistive Technology and Robotics (CNIT 581-AST, Course Eval: 4.75/5.0, Student#: 11), Purdue Univ. Fall 2016
- Introduction to Assistive Technology and Robotics (CNIT 581-AST, Course Eval: 4.75/5.0, Student#: 11), Purdue Univ. Fall 2015

POSTDOCS & STUDENTS

Postdocs

- Dr. Ramvijas Parasuraman 2016 –

Advisees

Current Students (6 Ph.D. students; 3 M.S. students; 2 Undergrad students)

- Wonse Jo: Ph.D., Technology 2017 –
- Tamzidul Mina: Ph.D., Mechanical Engineering (co-advised with Dr. Galen King) 2017 –
- Manoj Penmetcha: Ph.D., Technology 2016 –
- Shaocheng Luo: Ph.D., Technology 2016 –
- Sangjun Lee: Ph.D., Technology 2016 –
- Jun Han Bae: Ph.D., Technology 2015 –
- Shyam Sundar Kannan: M.S., Computer and Information Technology 2017 –
- Arabinda Samantaray: M.S., Computer and Information Technology 2016 –
- Yeonju Oh: M.S., Computer and Information Technology 2016 –
- Yongbum Cho: B.S., Mechanical Engineering 2016 –

– Jee Hwan Park: B.S., Mechanical Engineering 2016 –

Former Students (1 Undergrad students)

– Dong Hun Lee: B.S., Mechanical Engineering Technology 2017

Committee Member

Current Students (5 Ph.D. students; 5 M.S. students)

– Patchara Kitjacharoenchai: Ph.D., Industrial Engineering, Committee Chair: Dr. Seokcheon Lee 2017 –
– Yazeed Mohammad Al Babbain: Ph.D., Technology, Committee Chair: Dr. Justin Yang 2016 –
– Hanlin Chen: Ph.D., Technology, Committee Chair: Dr. John Springer 2016 –
– Mauricio Gomez: Ph.D., Technology, Committee Chair: Dr. Eric Matson 2015 –
– Daniel Schrader: Ph.D., Technology, Committee Chair: Dr. Eric Matson 2015 –
– Ho-Young Jeong: M.S., Industrial Engineering, Committee Chair: Dr. Seokcheon Lee 2017 –
– Austin Riegsecker: M.S., Computer and Information Technology, Committee Chair: Dr. Eric Matson and Prof. Tony Smith 2017 –
– Hyun Hwang: M.S., Computer and Information Technology, Committee Chair: Dr. Eric Matson 2017 –
– Zhenzhi Xu: M.S., Computer and Information Technology, Committee Chair: Dr. Justin Yang 2017 –
– Jin Hu: M.S., Mechanical Engineering Technology, Committee Chair: Dr. Xiumin Diao 2017 –

Former Students (1 Ph.D. students; 5 M.S. students)

– Amy Wagoner: Ph.D., Technology, Committee Chair: Dr. Eric Matson July 2017
– Sheifali Khare: M.S., Computer and Information Technology, Committee Chair: Prof. Alka Harriger July 2017
– Wang Tian: M.S., Computer and Information Technology, Committee Chair: Dr. Justin Yang May 2017
– Miae Kim: M.S., Computer and Information Technology, Committee Chair: Dr. Eric Matson May 2017
– Ji Yoon Lee: M.S., Computer and Information Technology, Committee Chair: Dr. Eric Matson May 2017
– Sang Mi Shin: M.S., Computer and Information Technology, Committee Chair: Dr. Eric Matson May 2016

PROFESSIONAL ACTIVITIES

Leadership Roles

– Co-organizer: The 1st U.S.-Korea PI Meeting to Explore US/Korea Joint Collaboration in Robotics and Related Areas (NSF workshop to Explore US/Korean Collaboration in Human-Friendly Co-Robotic Technologies) 2017
– Co-organizer: 2015 International Workshop on Communication for Humans, Agents, Robots, Machines and Sensors (CHARMS 2015) 2015
– Associate Technical Program Chair: the 6th International Conference on Automation, Robotics, and Applications (ICARA 2015) 2015

Editorial Boards

– Guest Editor: Technologies (MDPI) Special Issue on “Assistive Robotics” 2017 – Present
– Senior Editor: International Journal of Information Communication Technology and Digital Convergence 2016 – Present
– Guest Editor: Sensors (MDPI) Special Issue on “Integration of Sensors in Complex, Intelligent Systems” 2015 – 2016

Program Committee

– Program Committee: IEEE International Conference on Robotic Computing (IEEE IRC 2018) 2018
– Program Committee: 2018 International Workshop on Communication for Humans, Agents, Robots, Machines and Sensors (CHARMS 2018) 2018
– Program Committee: 2017 International Workshop on Communication for Humans, Agents, Robots, Machines and Sensors (CHARMS 2017) 2017
– International Program Committee: 14th International Conference on Ubiquitous Robots and Ambient Intelligence (URAI 2017) 2017
– International Program Committee: 8th International Conference on Social Robotics (ICSR) 2016
– International Program Committee: 13th International Conference on Ubiquitous Robots and Ambient Intelligence (URAI 2016) 2016
– Technical Program Committee: 2015 IEEE Sensors Applications Symposium (SAS 2015) 2015
– Technical Program Committee: International Workshop on Security and Privacy in Machine-to-Machine Communications (M2MSec'14) 2014

- Technical Program Committee: 2014 IEEE Sensors Applications Symposium (SAS 2014) 2014
- Program Committee: the 4th International Conference on Emerging Ubiquitous Systems and Pervasive Networks (EUSPN 2013) 2013

Grant Reviewer

- NSF 2017

Journal Reviewer

- Journal of Intelligent and Robotic Systems 2012 – 2017
- IEEE Transactions on Mobile Computing 2017
- ETRI Journal 2016, 2017
- Frontiers in Human Neuroscience 2016
- Journal of Field Robotics 2014, 2015
- Autonomous Robots 2015
- Soft Computing 2014, 2015
- IEEE Transactions on Haptics 2014
- IEEE Journal on Selected Areas in Communications 2014
- Journal of Mechanical Engineering Science 2014
- Multimedia Tools and Applications 2014
- IEEE Transactions on Mechatronics 2013
- Journal of Electromagnetic Waves and Applications 2013
- The Journal of Korea Information and Communications Society (J-KICS) 2013
- International Journal of Advanced Robotic Systems 2012
- Journal of Institute of Control, Robotics an Systems 2012

Conference Reviewer

- IEEE International Conference on Robotic Computing (IRC) 2017
- International Workshop on Communication for Humans, Agents, Robots, Machines and Sensors (CHARMS) 2016, 2017
- IEEE International Conference on Robotics and Automation (ICRA) 2015 – 2017
- International Conference on Social Robotics (ICSR) 2016
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2014, 2016
- IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN) 2016
- AAAI Conference on Artificial Intelligence (AAAI) 2015
- IEEE Sensors Applications Symposium (SAS) 2012 – 2015
- International Conference on Robot Intelligence Technology and Applications (RiTA) 2012, 2013
- International Conference on Control, Automation and Systems (ICCAS) 2010
- Chinese Control Conference (CCC) 2009

University Committee & Service

- Member: Purdue Robotics Accelerator Committee, Purdue University 2016 – Present

College Committee & Service

- Co-organizer: Purdue Polytechnic Postdoctoral Seminar Series, Purdue University 2017 – Present

Departmental Committee & Service

- Member: Faculty Search & Screen Committee, Computer and Information Technology, Purdue University 2017 – Present
- Co-chair: Election Committee, Computer and Information Technology, Purdue University 2017 – Present
- Member: Curriculum Committee, Computer and Information Technology, Purdue University 2016 – Present
- Member: Grad Education Committee, Computer and Information Technology, Purdue University 2016 – Present

PROFESSIONAL MEMBERSHIPS

Institute for Electrical and Electronics Engineers (IEEE), Student Member (2008 – 2014), Member 2014 – Present

Association for Computing Machinery (ACM), Member 2016 – Present

MORE INFORMATION

More information and auxiliary documents can be found at:
<http://web.ics.purdue.edu/~minb/> or
www.smart-laboratory.org.