

HW-2 Solns.

①

1. a) $y[n] = x^2[n]$.

(i) $2x[n] \rightarrow \boxed{\text{System}} \rightarrow 4x^2[n]$

Not Linear

(ii). Depends only on present value [or past]

∴ Causal

(iii). $x[n] \rightarrow \boxed{\text{System}} \rightarrow y[n] = x^2[n]$.

$x_1[n] = x[n-N] \rightarrow \boxed{\text{System}} \rightarrow y_1[n] = x^2[n-N] = y[n-N]$

∴ Time invariant.

(iv) $|x[n]| \leq B \rightarrow |y[n]| \leq B^2$

∴ Stable.

b) $y[n] = 5(n-1)x[n] + 2$.

~~(i) $y[n]$ depends on n~~

~~∴ Cannot~~

(i) $x[n] \rightarrow \boxed{\text{System}} \rightarrow y[n] = 5(n-1)x[n] + 2$

$ax[n] \rightarrow \boxed{\text{System}} \rightarrow y_1[n] = 5a(n-1)x[n] + 2 \neq ay[n]$.

∴ Not linear

②

(ii) . Depends only on present $x[n]$

\therefore Causal

(iii) . $y[n]$ depends on n

\therefore ~~Time~~ Time Variant.

(iv) . $x[n] = 1 \Rightarrow \lim_{n \rightarrow \infty} y[n] = \infty$

\therefore Not stable.

$$\Leftarrow y(t) = x(t+1) \cos(6\pi(t-1)).$$

(i) . $x(t) \rightarrow \boxed{\text{System}} \rightarrow y(t) = x(t+1) \cos(6\pi(t-1)).$

$$ax_1(t) \rightarrow \boxed{\text{System}} \rightarrow y_1(t) = a x(t+1) \cos(6\pi(t-1)) = a y(t).$$

$$x_1(t) + x_2(t) \rightarrow \boxed{\text{System}} \rightarrow y_2(t) = (x_1(t+1) + x_2(t+1)) \cos(6\pi(t-1)) \\ = x_1(t+1) \cos(6\pi(t-1)) + x_2(t+1) \cos(6\pi(t-1))$$

\therefore Linear.

(ii) $y(t)$ Depends on $x(t+1)$ [Future values].

\therefore Not Causal

(iii) $y(t)$ has $\cos(6\pi(t-1))$ which depends on t

\therefore Time variant .

$$(iv) \text{ Let } |x(t)| \leq B$$

(3)

$$\text{We know } |\cos(6\pi(t-1))| \leq 1.$$

$$\Rightarrow |y(t)| \leq B$$

\therefore Stable.

$$d) y(t) = e^{-10t} x(t).$$

$$(i) \quad ax_1(t) + bx_2(t) \rightarrow \boxed{\text{System}} \rightarrow y'(t) = e^{-10t}(ax_1(t) + bx_2(t)) \\ = ax_1(t)e^{-10t} + bx_2(t)e^{-10t}$$

\therefore Linear.

(ii) Depends only on present values

\therefore Causal

(iii) e^{-10t} depends on 't'

\therefore Time variant

$$(iv) \quad x(t) = 1.$$

$$\lim_{t \rightarrow -\infty} y(t) = \infty$$

$$e) \quad y(t) = e^{-10jt} x(t).$$

(i) Similar to (d). Linear

(4)

(ii). Depends only on present values of x

\therefore Causal

(iii). Similar to (d). Time Variant

(iv). Let $|x(t)| \leq B$.

$$|e^{-10j^2 t}| = 1.$$

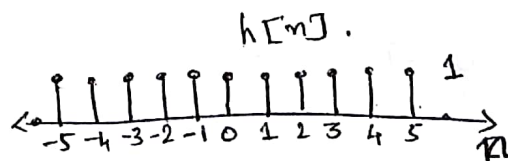
$$\Rightarrow |y(t)| \leq B.$$

\therefore Stable.

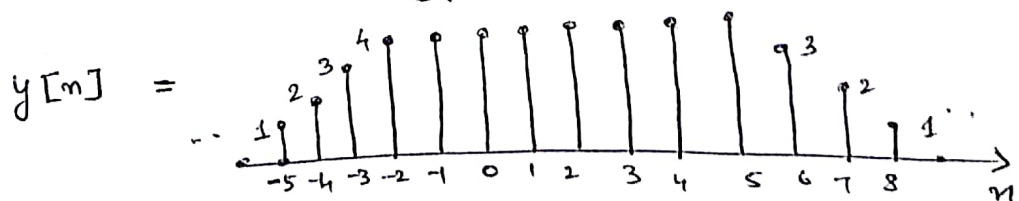
$$2. \quad y[n] = \sum_{i=n-5}^{n+5} x[i].$$

$$y[n] = \sum_{i=-5}^5 x[n+i].$$

$$a) \quad x[n] = \delta[n] \Rightarrow h[n] = \sum_{i=-5}^5 \delta[n+i].$$



$$b) \quad x[n] =$$



c) (i) ~~D&B~~ $y[n]$ depends on future values (5)

\therefore Not Causal.

(ii) Not memoryless.

Uses more than just the present value of x $x[n]$.

(iii). Let $|x[n]| \leq B$

$$\Rightarrow |y[n]| \leq 11B$$

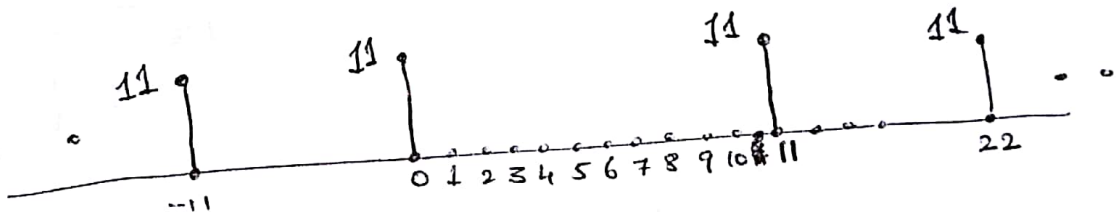
\therefore stable

(iv). Consider

$$x[n] = 1 \quad \forall n.$$

$$y[n] = 11 \quad \forall n.$$

now consider the signal.

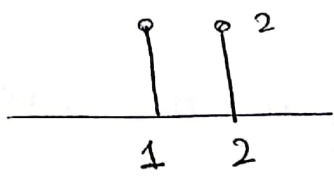


$$y[n] = 11 \quad \forall n.$$

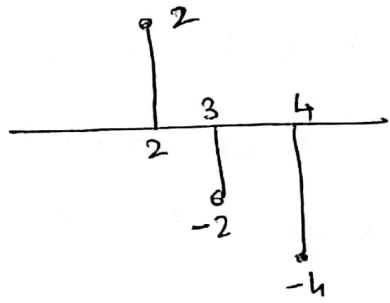
\therefore System is not invertible.

3.

a). $x_1[n]$



$x_2[n]$

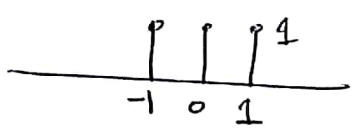


Notice: $x_2[n] = x_1[n-1] - 2x_1[n-2]$.

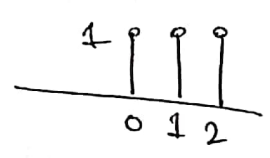
System is LTI

$$\therefore y_2[n] = y_1[n-1] - 2y_1[n-2]$$

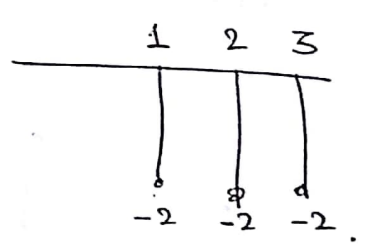
$y_1[n]$



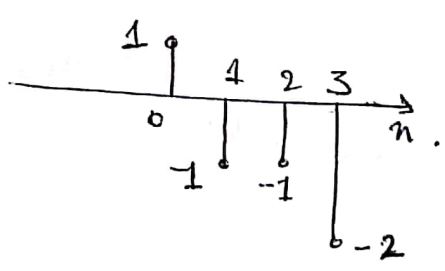
$y_1[n-1]$



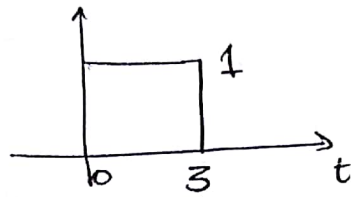
$-2y_1[n-2]$



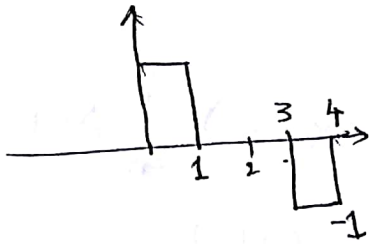
$y_2[n]$



b). $x_1(t)$



$x_2(t)$

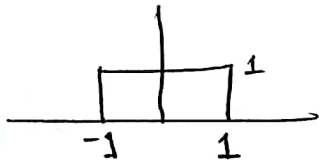


Notice:

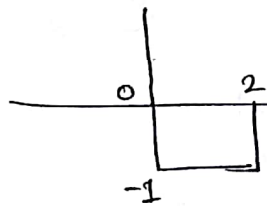
$$x_2(t) = x_1(t) - x_1(t-1)$$

System is LTI $\Rightarrow y_2(t) = y_1(t) - y_1(t-1)$

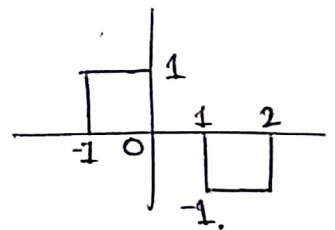
$y_1(t)$



$-y_1(t-1)$



$y_2(t)$



4. $y(t) = x(t) * h(t)$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$x(t+t_1) * h(t-t_2) = \int_{-\infty}^{\infty} x(\tau+t_1) h(t-t_2-\tau) d\tau$$

~~assume~~ (let $\tau' = \tau + t_1 \Rightarrow \tau = \tau' - t_1$)

$$= \int_{-\infty}^{\infty} x(\tau') h(t-t_2-\tau'+t_1) d\tau'$$

$$= \int_{-\infty}^{\infty} x(\tau') h((t-(t_2-t_1))-\tau') d\tau'$$

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$$\int_{-\infty}^{\infty} x(\tau') h((t - (t_2 - t_1)) - \tau') d\tau' = \underline{y(t - (t_2 - t_1))}.$$

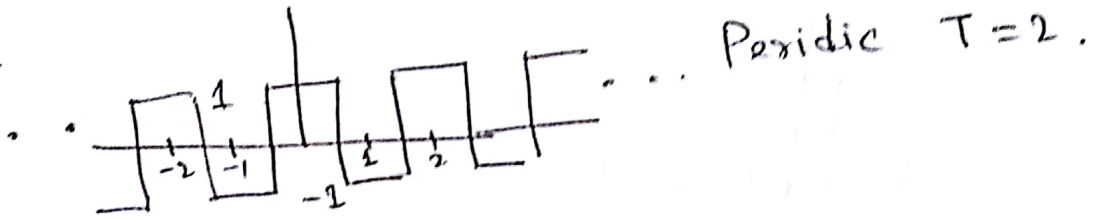
$$\begin{aligned} \text{b) } \int_{-\infty}^{\infty} x(t) \delta(t - t_0) dt &= \int_{-\infty}^{\infty} x(t_0) \delta(t - t_0) dt \\ &= x(t_0) \int_{-\infty}^{\infty} \delta(t - t_0) dt \\ &= x(t_0) \end{aligned}$$

$$\begin{aligned} \text{c) } \int_{-\infty}^{\infty} x(\tau) \delta(t + t_0 - \tau) d\tau &= \int_{-\infty}^{\infty} x(t + t_0) \delta(t + t_0 - \tau) d\tau \\ &= x(t + t_0) \int_{-\infty}^{\infty} \delta(t + t_0 - \tau) d\tau \\ &= x(t + t_0). \end{aligned}$$

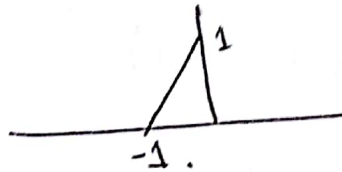
$$\begin{aligned} \text{d) } \int_{-\infty}^{\infty} x(\tau) \delta(t + \tau) d\tau &= \int_{-\infty}^{\infty} x(-t) \delta(t + \tau) d\tau \\ &= x(-t) \int_{-\infty}^{\infty} \delta(t + \tau) d\tau \\ &= x(-t). \end{aligned}$$

5.

a) $x(t)$.



$y(t)$



$$z(t) = x(t) * y(t)$$

$$x(t) = \sum_{k=-\infty}^{\infty} x_p(t-kT)$$

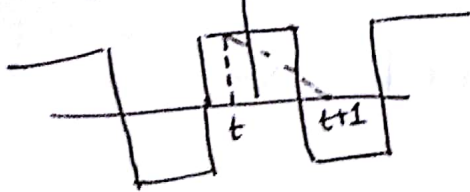
$$z(t) = \left(\sum_{k=-\infty}^{\infty} x_p(t-kT) \right) * y(t)$$

$$z(t) = \sum_{k=-\infty}^{\infty} (x_p(t-kT) * y(t))$$

$\because x(t)$ is periodic $z(t)$ is also periodic with $T=2$. So it is enough if we find $z(t)$

for one period. Let us find for $-0.5 \leq t \leq 1.5$.

(i) $-0.5 \leq t \leq 0.5$



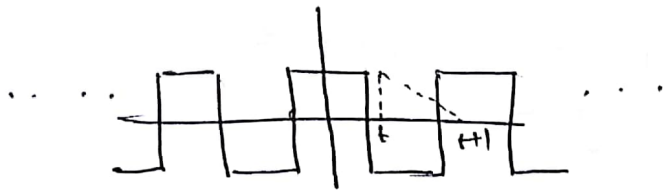
$$y(t) = \frac{1}{2} - 2 \cdot \left(\frac{1}{2} (t+1-0.5)^2 \right)$$

$$= \frac{1}{2} - (t+0.5)^2$$

$$= \frac{1}{2} - t^2 - t - \frac{1}{4}$$

$$y(t) = -t^2 - t + \frac{1}{4} \quad -0.5 \leq t \leq 0.5$$

(ii) $0.5 \leq t \leq 1.5$



$$\begin{aligned}
 y(t) &= -\frac{1}{2} + 2\left(\frac{1}{2}(t+1-1.5)^2\right) \\
 &= -\frac{1}{2} + (t-0.5)^2 \\
 &= -\frac{1}{2} + t^2 - t + 0.25 \\
 &= t^2 - t - \frac{1}{4}
 \end{aligned}$$

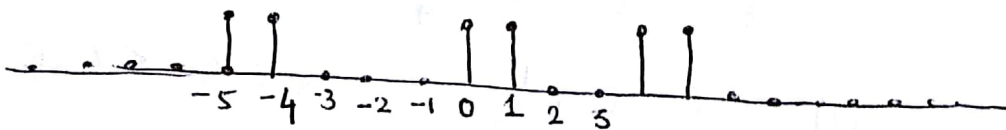
For one period $y(t) = \begin{cases} -t^2 - t + \frac{1}{4} & -0.5 \leq t \leq 0.5 \\ t^2 - t - \frac{1}{4} & 0.5 \leq t \leq 1.5 \end{cases}$

b). $x[n] = \delta[n+5] + \delta[n-4] + \delta[n]$.

$y[n] = u[n] - u[n-2]$. Note: $x[n] * \delta[n-N] = x[n-N]$

$$\begin{aligned}
 x[n] * y[n] &= u[n+5] + u[n-4] + u[n] \\
 &\quad - u[n+3] - u[n-6] - u[n-2].
 \end{aligned}$$

$x[n] * y[n]$.



$x[n]$

$L 2 - , ,$

(11)

$$c. \quad x_1[n] = \left(\frac{1}{3}\right)^n u[n].$$

$$x_2[n] = u[n]$$

$$x_3[n] = \delta[n-2].$$

$$x_1[n] * x_2[n] * x_3[n]$$

$$= x_1[n] * [x_2[n] * x_3[n]]$$

$$= \left(\left(\frac{1}{3}\right)^n u[n]\right) * [u[n] * \delta[n-2]]$$

$$= \left(\left(\frac{1}{3}\right)^n u[n]\right) * [u[n-2]].$$

$$x[n] * y[n] = \sum_{k=-\infty}^{\infty} x[k] y[n-k].$$

$$x[n] = \left(\frac{1}{3}\right)^n u[n] \quad y[n] = u[n-2].$$

$$\Rightarrow \sum_{k=-\infty}^{\infty} \left(\frac{1}{3}\right)^k u[k] \cdot u[n-2-k]$$

$$= \sum_{k=0}^{\infty} \left(\frac{1}{3}\right)^k u[n-2-k] = 0 \quad \text{if } n < 2$$

$$\text{For } n \geq 2. \quad \sum_{k=0}^{\infty} \left(\frac{1}{3}\right)^k u[n-2-k] = \sum_{k=0}^{n-2} \left(\frac{1}{3}\right)^k = \frac{1 - \left(\frac{1}{3}\right)^{n-1}}{1 - \frac{1}{3}}$$

$$x_1[n] * x_2[n] * x_3[n] = \begin{cases} 0 & n < 2 \\ \frac{3}{2} \cdot \left(1 - \left(\frac{1}{3}\right)^{n-1}\right) & n \geq 2 \end{cases} = \frac{3}{2} \cdot \left(1 - \left(\frac{1}{3}\right)^{n-1}\right).$$