

Invertibility of LTI Systems

An LTI System with impulse response $h(t)$ is invertible if there is a signal $h_1(t)$ such that $h(t) * h_1(t) = \delta(t)$

Examples

$$h(t) = \delta(t - t_0)$$

$$y(t) = x(t) * h(t)$$

$$= \int x(\tau) h(t - \tau) d\tau$$

$$= \int_{-\infty}^{\infty} x(\tau) \delta(t - t_0 - \tau) d\tau$$

$$= x(t - t_0)$$

(2)

We know that the inverse system

$$y_1(t) = x_1(t + t_0)$$

$$h_1(t) = \delta(t + t_0)$$

Let's verify that $h(t) * h_1(t) = \delta(t)$

$$\begin{aligned} h(t) * h_1(t) &= \delta(t - t_0) * \delta(t + t_0) \\ &= \int_{-\infty}^{\infty} \delta(\tau - t_0) \delta(t + t_0 - \tau) d\tau \\ &= \delta(t + t_0 - t_0) = \delta(t) \end{aligned}$$

Example

(3)

$$h[n] = u[n]$$

$$y[n] = x[n] * h[n]$$

$$= \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$= \sum_{k=-\infty}^{\infty} x[k] u[n-k]$$

$$= \sum_{k=-\infty}^n x[k]$$

Accumulator

$$y[n] - y[n-1] = \sum_{k=-\infty}^n x[k] - \sum_{k=-\infty}^{n-1} x[k]$$

$$= x[n]$$

The inverse system to the accumulator (4)

is the differentiator

$$y_1[n] = x_1[n] - x_1[n-1]$$

$$h_1[n] = \delta[n] - \delta[n-1]$$

Verification

$$h[n] * h_1[n] = u[n] * [\delta[n] - \delta[n-1]]$$

$$= u[n] * \delta[n] - u[n] * \delta[n-1]$$

$$= u[n] - u[n-1]$$

$$= \delta[n] \quad \checkmark$$

The unit-step response

(5)

$$s[n] = u[n] * h[n]$$

$$= h[n] * u[n]$$

$$= \sum_{k=-\infty}^{\infty} h[k] u[n-k]$$

$$= \sum_{k=-\infty}^n h[k]$$

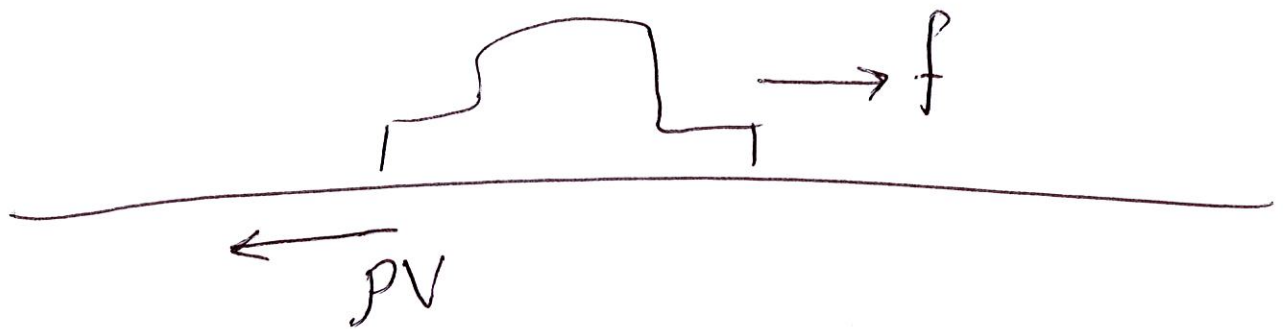
$$h[n] = ~~u[n]~~ s[n] - s[n-1]$$

CT

$$s(t) = \int_{-\infty}^t h(\tau) d\tau$$

$$h(t) = \frac{d s(t)}{dt}$$

Systems described by linear
constant coefficient differential equations (6)



$$\frac{dv(t)}{dt} = \frac{1}{m} [f(t) - p v(t)]$$

$$\frac{dv(t)}{dt} + \frac{p}{m} v(t) = \frac{1}{m} f(t)$$

$$\frac{dy(t)}{dt} + a y(t) = b x(t)$$

Constants

First-order
diff. equ.

(7)

$$\frac{dy(t)}{dt} + 2y(t) = x(t) \quad (*)$$

$$x(t) = k e^{3t} u(t)$$

$$y(t) = y_p(t) + y_h(t)$$

$y_p(t)$ is a solution to (*)

$y_h(t)$ is a solution to

$$\frac{dy_h(t)}{dt} + 2y_h(t) = 0$$

Finding $y_p(t)$

Assume $y_p(t) = \overset{\text{constant}}{y} e^{3t}$

$$3y e^{3t} + 2y e^{3t} = k e^{3t}, \quad t \geq 0$$

(8)

$$y = \frac{k}{s}$$

$$y_p(t) = \frac{k}{s} e^{3t} \quad \text{with } t > 0$$

Finding $y_h(t)$

$$\frac{dy_h(t)}{dt} + 2y_h(t) = 0$$

Assume $y_h(t) = A e^{st}$ ← Constant

$$As e^{st} + 2A e^{st} = 0$$

$$A e^{st} (s+2) = 0$$

$$\Rightarrow s = -2$$

$$y_h(t) = A e^{-2t}$$

$$y(t) = y_p(t) + y_h(t)$$

$$= \frac{k}{s} e^{3t} + A e^{-2t}, \quad t > 0$$

