

Midterm 1 - Monday Sep. 24 In-Class

5 Problems (30 pts - 3% each)

1 ~~err~~ sheet (Back and Front) allowed

Revise: Notes - HW 1 - Q1 & 2 - F'17 & S'18
(82) Exam 1

$$\frac{dy(t)}{dt} + 2y(t) = x(t)$$

$$x(t) = k e^{3t} u(t)$$

$$y(t) = A e^{-2t} + \frac{k}{5} e^{3t}, \quad t > 0$$

(2)

The condition of initial rest

$$y(0) = 0$$

$$A e^{-2t} + \frac{k}{s} e^{3t} \Big|_{t=0} = 0$$

$$A + \frac{k}{s} = 0$$

$$A = -\frac{k}{s}$$

$$\Rightarrow y(t) = \frac{k}{s} [e^{3t} - e^{-2t}] u(t)$$

Systems described by linear constant-coefficient difference equations (3)

$$\sum_{k=0}^N a_k y[n-k] = \sum_{k=0}^M b_k x[n-k] \quad (*)$$

\rightarrow N-th order

With the condition of initial rest, the system described by (*) is LTI and Causal

$$y[n] = \frac{1}{a_0} \left[\sum_{k=0}^M b_k x[n-k] - \sum_{k=1}^N a_k y[n-k] \right]$$

Example

(4)

$$y[n] - \frac{1}{2} y[n-1] = x[n]$$

$$y[n] = x[n] + \frac{1}{2} y[n-1]$$

Assume initial rest and

$$x[n] = k \delta[n]$$

$$y[n] = \left(\frac{1}{2}\right)^n k u[n]$$

$$y[n] = 0 \quad \text{for } n < 0$$

$$\begin{aligned} y[0] &= x[0] + \frac{1}{2} y[-1] \\ &= k \end{aligned}$$

$$\begin{aligned} y[1] &= x[1] + \frac{1}{2} y[0] \\ &= \frac{k}{2} \end{aligned}$$

$$y[2] = x[2] + \frac{1}{2} y[1] = \frac{k}{4}$$

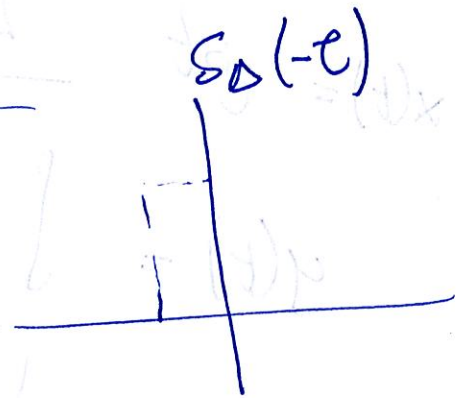
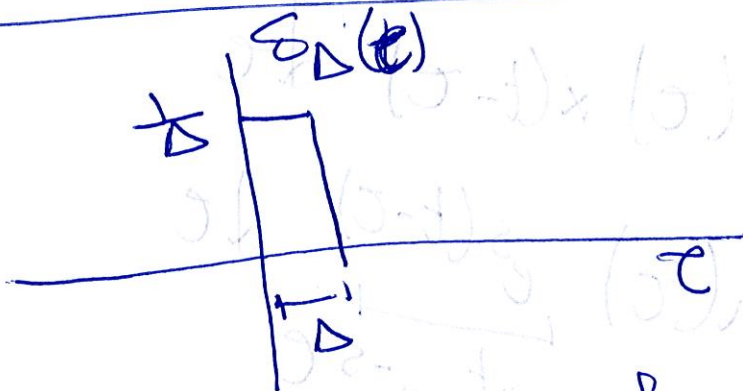
$$y[n] - \frac{1}{2} y[n-1] = x[n]$$

with initial rest

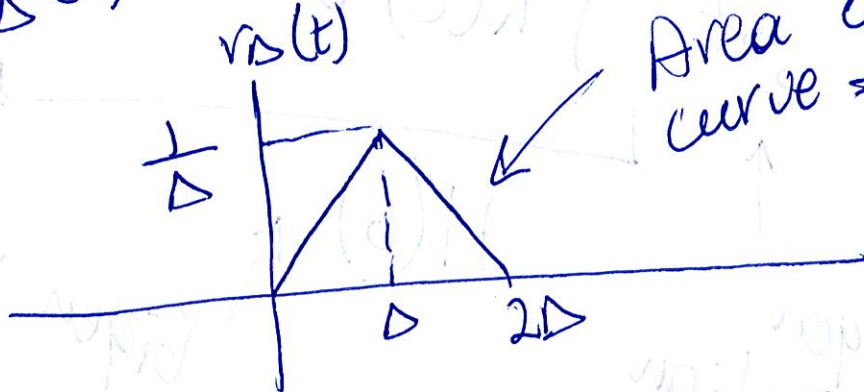
$$h[n] = \left(\frac{1}{2}\right)^n u[n]$$

IIR System

Singularity Functions



$$\delta_\Delta(t) * \delta_\Delta(t) = \int \delta_\Delta(\tau) \delta_\Delta(t-\tau) d\tau$$



Area under the curve = 1

$$\lim_{\Delta \rightarrow 0} \delta_\Delta(t) = \delta(t)$$

$$\lim_{\Delta \rightarrow 0} r_\Delta(t) = \delta(t)$$

$$\lim_{\Delta \rightarrow 0} \delta_{\Delta}(t) * r_{\Delta}(t) = \delta(t)$$

(6)

Fourier Series Representation of Periodic Signals

$$x(t) = e^{st} \xrightarrow{\text{LTI}} ?$$

$$y(t) = \int h(\tau) x(t-\tau) d\tau$$

$$= \int h(\tau) \frac{e^{s(t-\tau)}}{e^{st} e^{-s\tau}} d\tau$$

$$\underbrace{e^{st}}_{\substack{\uparrow \\ \text{Eigen} \\ \text{function}}} \underbrace{\int h(\tau) e^{-s\tau} d\tau}_{\substack{\uparrow \\ H(s) \\ \text{Eigen value}}}$$

CT

$$\text{est LTI} \rightarrow \text{est } H(s) = (s)$$

DT
 $x[n]$

$$z^n \xrightarrow{\text{LTI}} ?$$

$$y[n] = x[n] * h[n]$$

$$= h[n] * x[n]$$

$$= \sum_k h[k] x[n-k]$$

$$= \sum_k h[k] z^{n-k}$$

$$= z^n \sum_k h[k] z^{-k}$$

$$\underbrace{\hspace{10em}}_{H(z)}$$

Example

(8)

$$y(t) = x(t-3)$$

$$x(t) = e^{j2t}$$

$$y(t) = e^{j(2t-6)} = \underbrace{e^{-j6}}_{H(j2)} e^{j2t}$$

$$H(s) = \int h(\tau) e^{-s\tau} d\tau$$

$$= \int \delta(\tau-3) e^{-s\tau} d\tau$$

$$= e^{-3s}$$

$$\Rightarrow H(j2) = e^{-6j}$$

$$\Rightarrow y(t) = e^{j2t} e^{-6j}$$

$$x_2(t) = e^{j3t} \Rightarrow y(t) = e^{j3t} e^{-9j}$$