

Examples on convolution property

$$y(t) = x(t) * h(t) \leftarrow \begin{array}{l} \text{Impulse response} \\ \text{of an LTI system} \end{array}$$

$$Y(j\omega) = X(j\omega) H(j\omega)$$

\uparrow
Frequency response
of the LTI system

Example 4.15

$$h(t) = \delta(t - t_0)$$

\leftarrow shifting by t_0
to the right

$$H(j\omega) = \int_{-\infty}^{\infty} h(t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} \delta(t - t_0) e^{-j\omega t} dt = e^{-j\omega t_0}$$

$$Y(j\omega) = X(j\omega) e^{-j\omega t_0}$$

$$y(t) = x(t - t_0)$$

Example 4-16

(2)

$$y(t) = \frac{dx(t)}{dt}$$

$$Y(j\omega) = j\omega X(j\omega)$$

$$H(j\omega) = j\omega \leftarrow \begin{array}{l} \text{Frequency Response} \\ \text{of Differentiator} \end{array}$$

Example 4-17

$$y(t) = \int_{-\infty}^t x(\tau) d\tau$$

$$H(j\omega) = \frac{1}{j\omega} + \pi \delta(\omega)$$

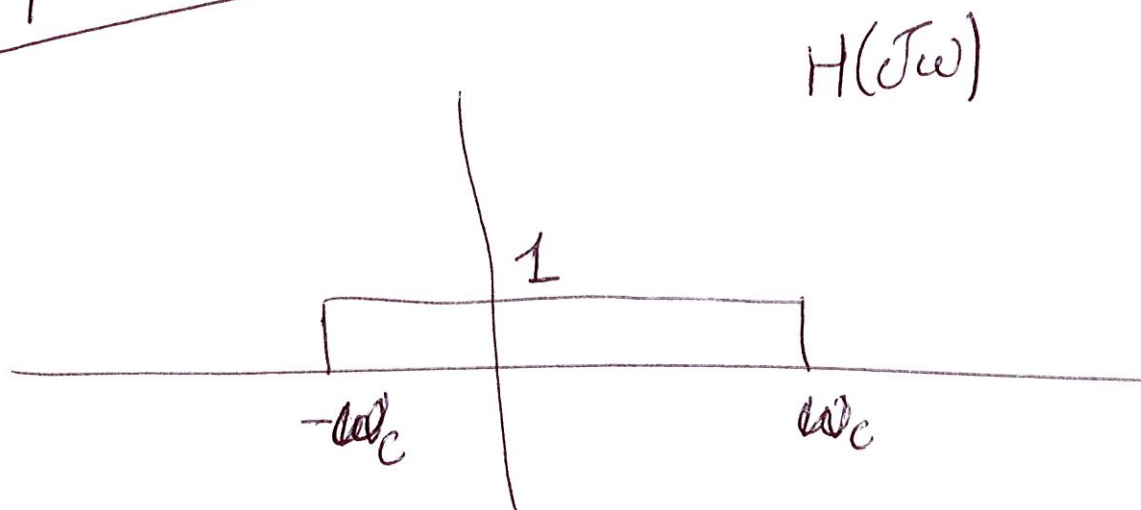
$$Y(j\omega) = X(j\omega) H(j\omega)$$

$$= \frac{X(j\omega)}{j\omega} + \pi X(j\omega) \delta(\omega)$$

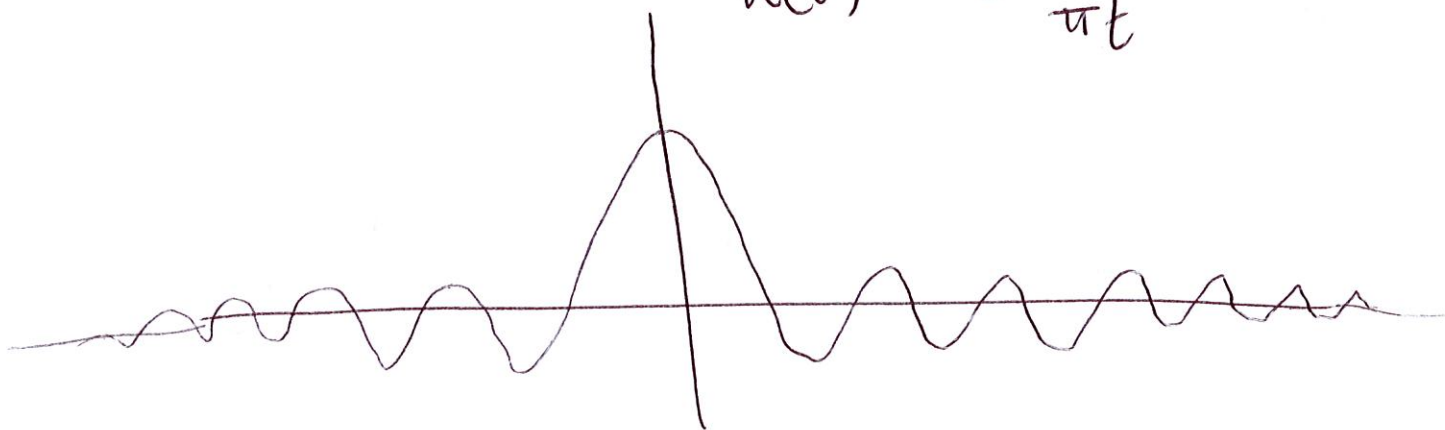
$X(0)$

Example 4-18

(3)



$$h(t) = \frac{\sin \omega_c t}{\pi t}$$

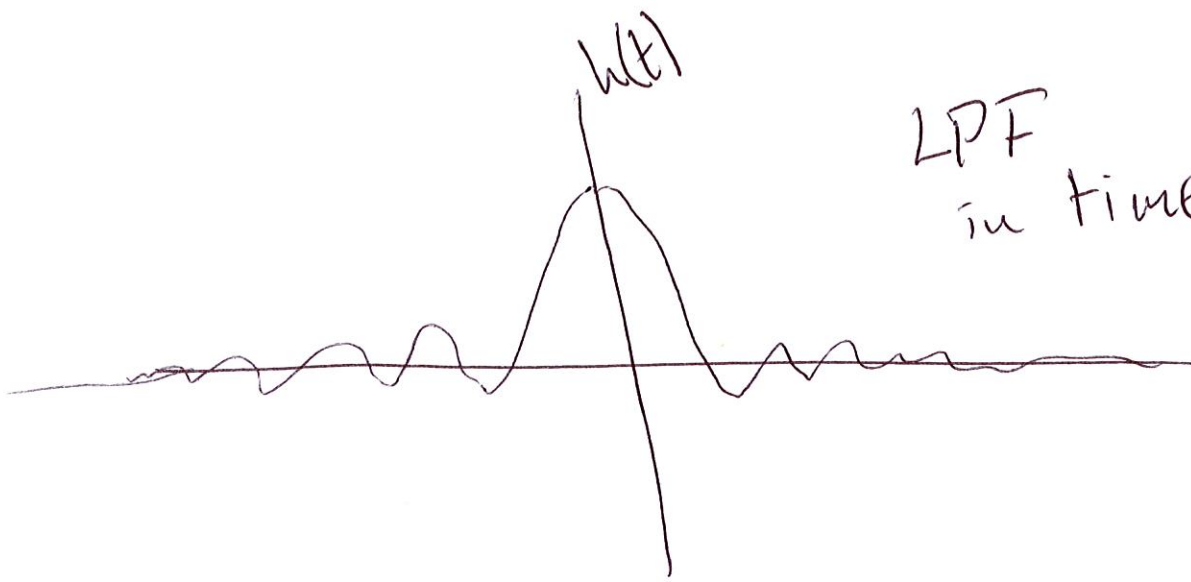


$$Y(j\omega) = X(j\omega) H(j\omega)$$

$$= \begin{cases} X(j\omega) & , \quad -\omega_c \leq \omega \leq \omega_c \\ 0 & , \quad |\omega| > \omega_c \end{cases}$$

Low Pass filter (LPF)

(4)



LPT
in time domain

Practical Issues

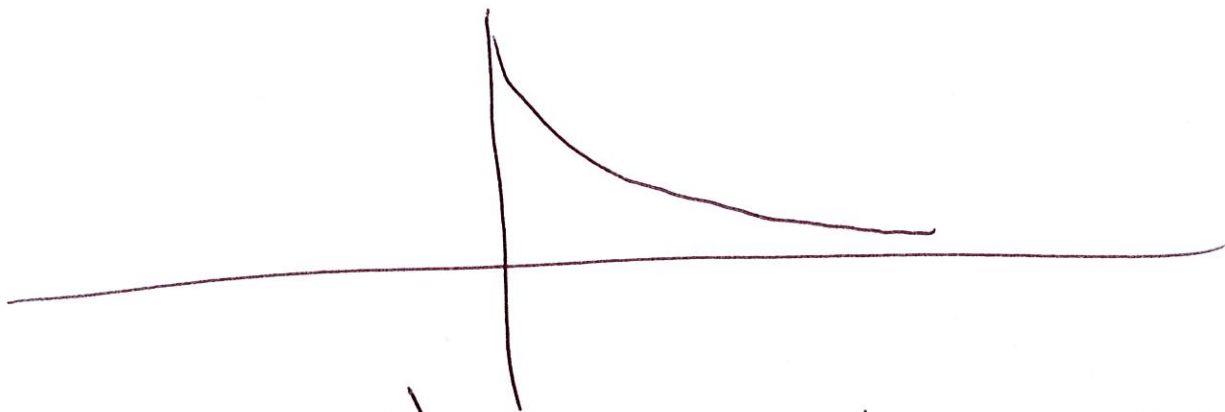
- Non-Causal, because $h(t) \neq 0$
for $t < 0$

- Oscillatory behavior

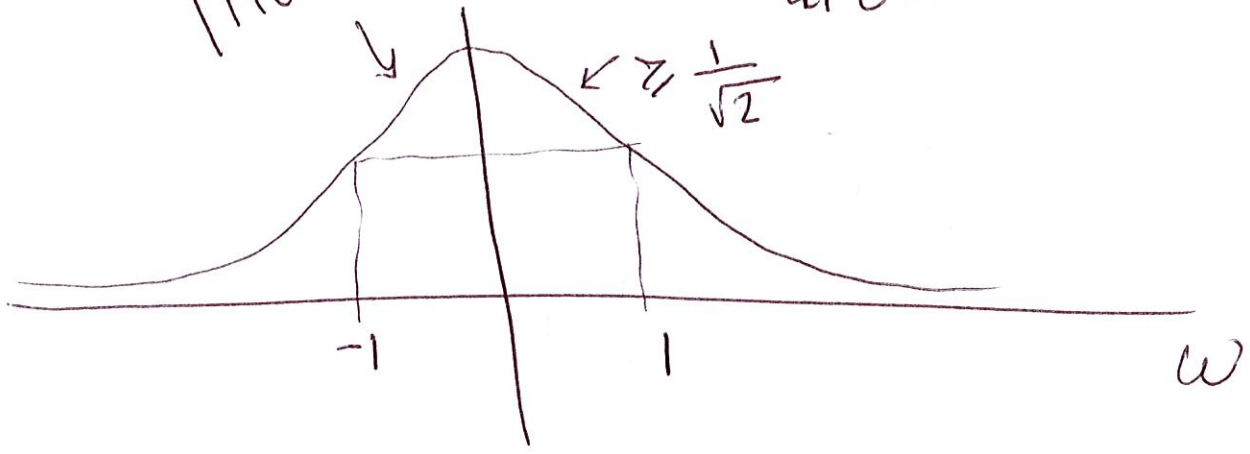
Approximation to LPF

(5)

$$h(t) = e^{-at} u(t), \quad a > 0$$



$$|H(j\omega)| \quad H(j\omega) = \frac{1}{a + j\omega} \quad a = 1$$



Example 4-19

(6)

$$h(t) = e^{-at} u(t), \quad a > 0$$

$$x(t) = e^{-bt} u(t), \quad b > 0$$

$$H(j\omega) = \frac{1}{a + j\omega}$$

$$X(j\omega) = \frac{1}{b + j\omega}$$

$$Y(j\omega) = \frac{1}{(a + j\omega)(b + j\omega)}$$

Partial fraction expansion

$$Y(j\omega) = \frac{A}{a + j\omega} + \frac{B}{b + j\omega}$$

$$1 = A(b + j\omega) + B(a + j\omega)$$

(7)

$$A \mathcal{J}\omega + B \mathcal{J}\omega = 0$$

$$\Rightarrow A = -B$$

$$1 = Ab + Ba$$

$$1 = A(b-a)$$

$$\Rightarrow A = \frac{1}{b-a} \quad B = -\frac{1}{b-a}$$

$$Y(\mathcal{J}\omega) = \frac{1}{b-a} \left[\frac{1}{a+\mathcal{J}\omega} - \frac{1}{b+\mathcal{J}\omega} \right]$$

$$y(t) = \frac{1}{b-a} \left[e^{-at} - e^{-bt} \right] u(t)$$

If $b \neq a$

If $b=a$

$$Y(s) = \frac{1}{(a+js)^2} = \frac{1}{-j} \left[\frac{d}{ds} (a+js)^{-1} \right]$$

$$-1 (a+js)^{-2} \cdot j$$

$$= j \frac{d}{ds} \left[\frac{1}{a+js} \right] \quad y(t) = t e^{-at} u(t)$$

$$\begin{aligned} x(t) &\xleftrightarrow{\mathcal{F}} X(s) \\ -jt x(t) &\xleftrightarrow{\mathcal{F}} \frac{d}{ds} X(s) \end{aligned}$$

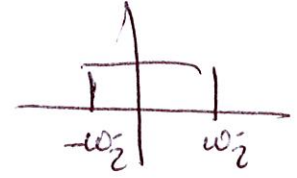
$$x(t) = e^{-at} u(t) \xleftrightarrow{\mathcal{F}} \frac{1}{a+js}$$

$$\underbrace{j, -j}_{1} t e^{-at} u(t) \xleftrightarrow{\mathcal{F}} j \frac{d}{ds} \left[\frac{1}{a+js} \right]$$

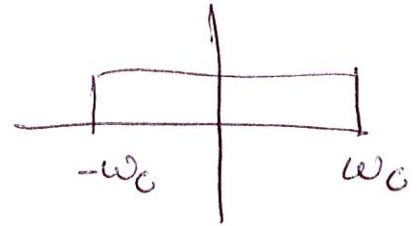
Example 4.20

(9)

$$x(t) = \frac{\sin \omega_i t}{\pi t}$$



$$h(t) = \frac{\sin \omega_c t}{\pi t}$$



$$x(t) * h(t) = \begin{cases} \frac{\sin \omega_i t}{\pi t} & \text{if } |\omega_i| \leq |\omega_c| \\ \frac{\sin \omega_c t}{\pi t} & \text{otherwise} \end{cases}$$

The Multiplication Property

$$r(t) = s(t) p(t) \xleftrightarrow{\mathcal{F}} R(j\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S(j\theta) P(j(\omega - \theta)) d\theta$$

(10)

$$p(t) = \cos \omega_0 t$$

$$P(j\omega)$$



$$S(j\omega)$$

