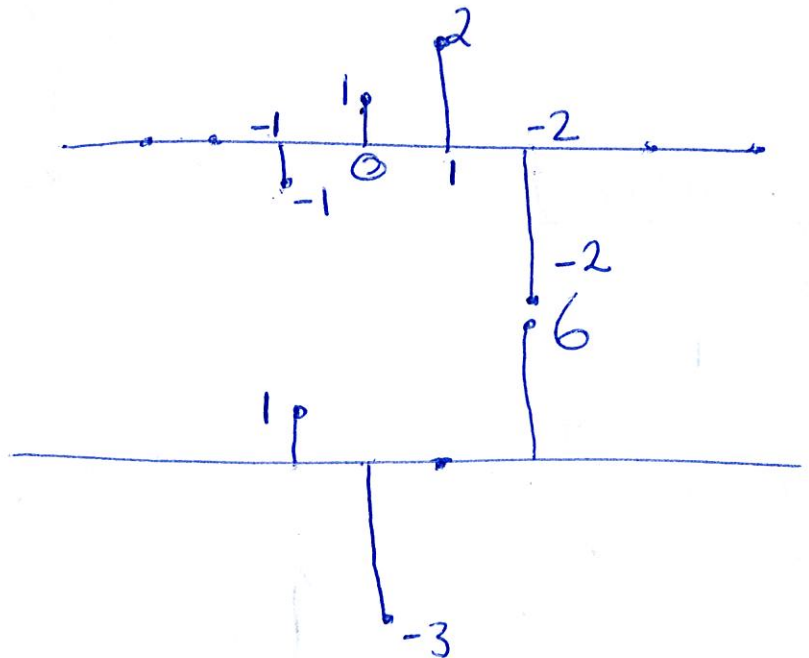


Time Invariance

Any shift in the input signal, results in the same shift in the output signal, and this is true for any input signal

Examples

$$y[n] = 2x[n-1] - x[n] \quad \text{Time Invariant}$$



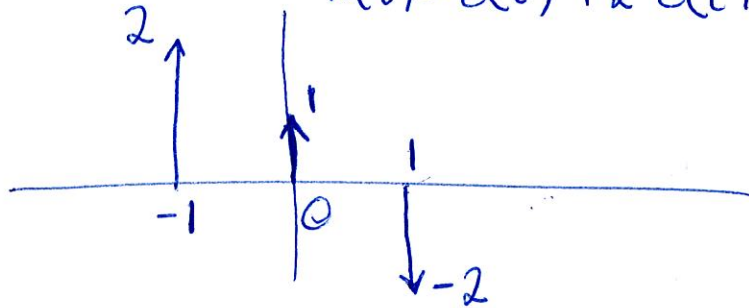
(2)

$y[n] = (n-1)x[n]$  Time Variant

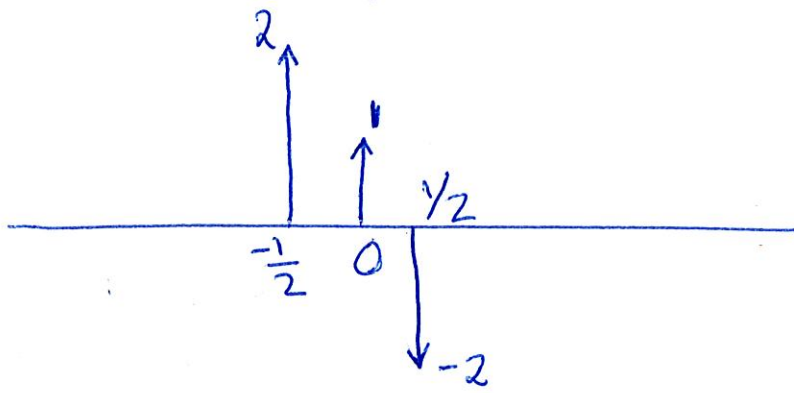
$y(t) = x(2t)$

Time Invariant? No

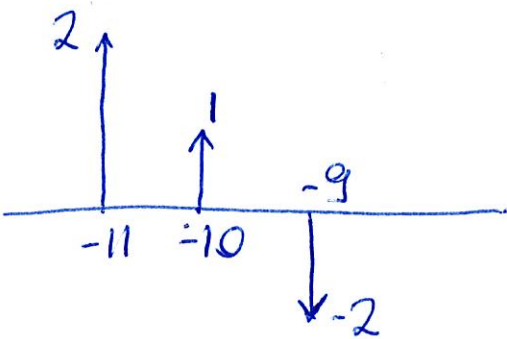
$x(t) = \delta(t) + 2\delta(t+1) - 2\delta(t-1)$



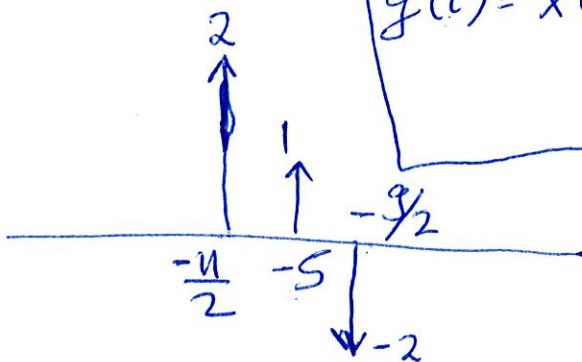
$y(t) = x(2t)$



$\tilde{x}(t) = x(t+10)$



$\tilde{y}(t) = \tilde{x}(2t) = y(t+5) \neq y(t+10)$



# Linear and Time Invariant (LTI) Systems

(3)

Consider any DT signal  $x[n]$

$$x[n] \delta[n] = \begin{cases} x[0] & \text{if } n=0 \\ 0 & \text{otherwise} \end{cases}$$

$\uparrow$   
 $\begin{cases} 1 & n=0 \\ 0 & \text{otherwise} \end{cases}$

$$x[n] \delta[n-1] = \begin{cases} x[1] & \text{if } n=1 \\ 0 & \text{otherwise} \end{cases}$$

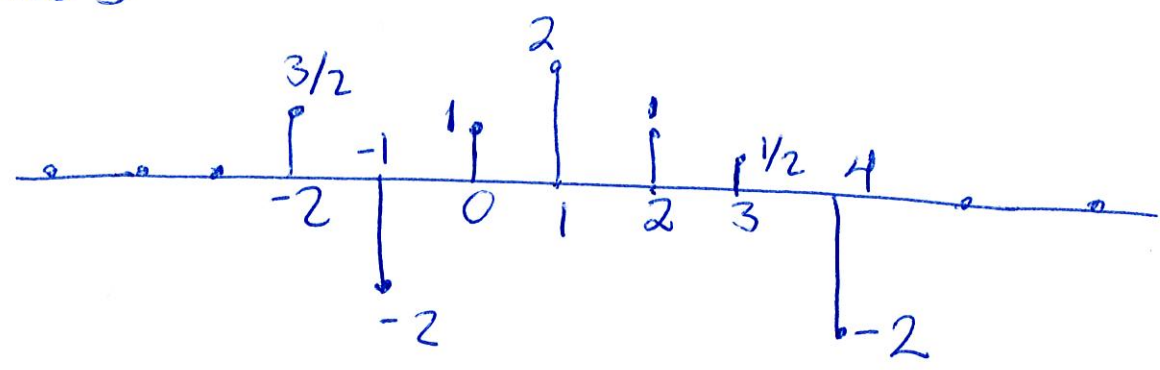
$\uparrow$   
 $\begin{cases} 1 & n=1 \\ 0 & \text{otherwise} \end{cases}$

$$x[n] \delta[n+1] = \begin{cases} x[-1] & \text{if } n=-1 \\ 0 & \text{otherwise} \end{cases}$$

Ex

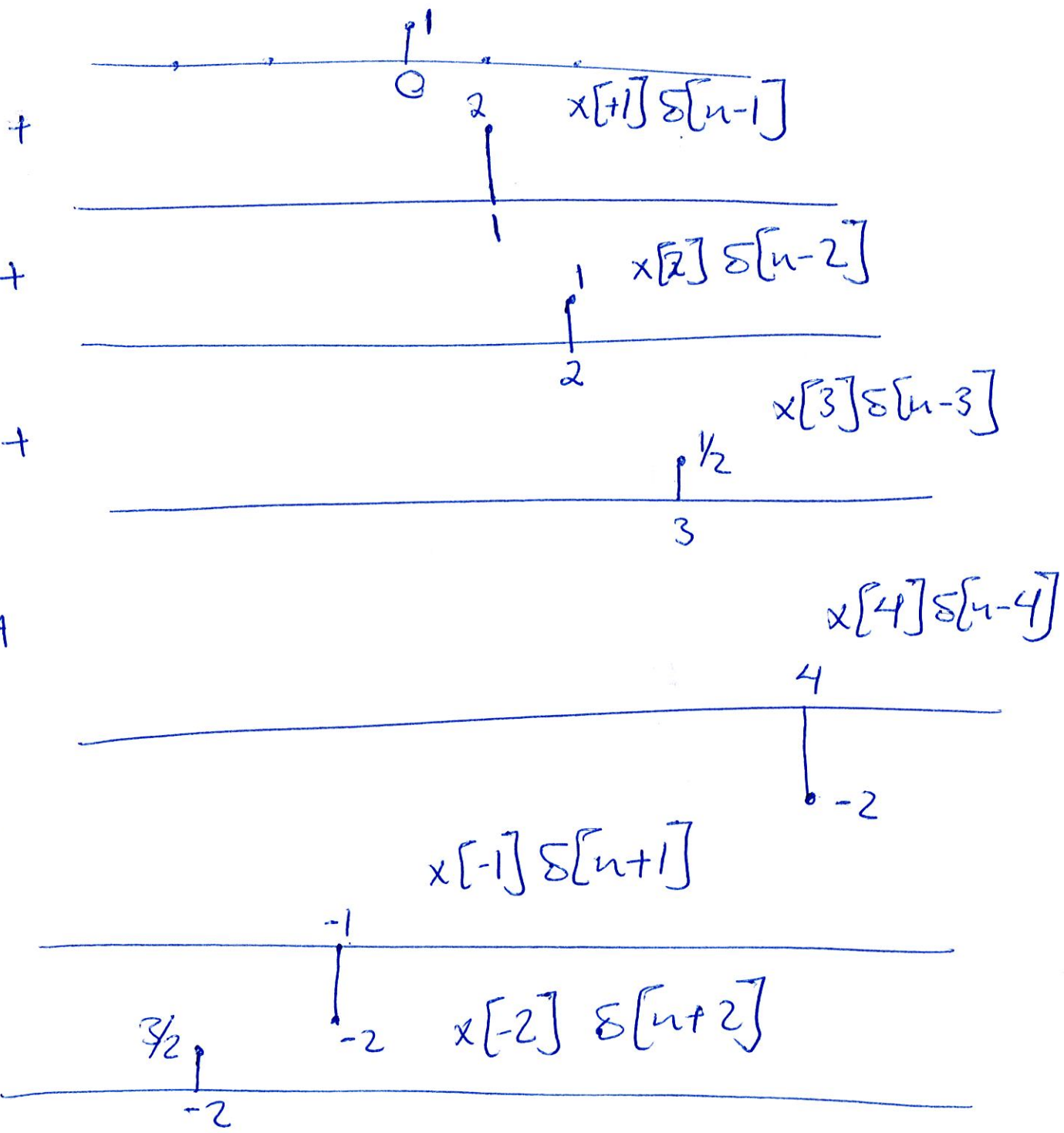
$x[n]$

(4)



=

$$x[n] \delta[n] = \delta[n]$$



$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$$

(5)

↓ Input to an LTI System

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h_k[n]$$

By Linearity

Response to  $\delta[n-k]$

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k] \triangleq x[n] * h[n]$$

where  $h[n]$  is the output when  
the input is  $\delta[n]$

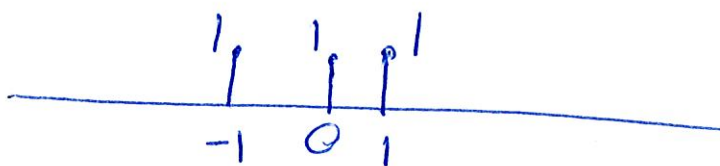
Impulse Response



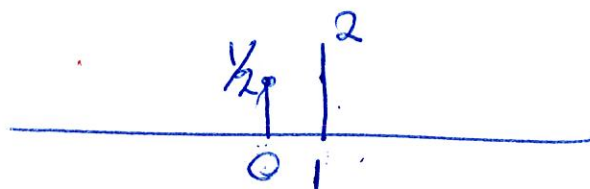
# Example 2-1

(6)

$h[n]$

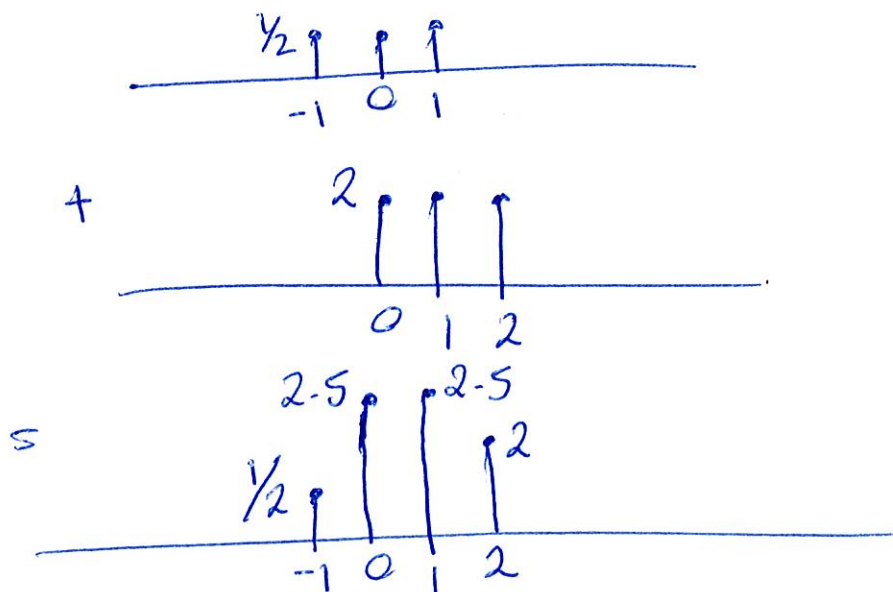


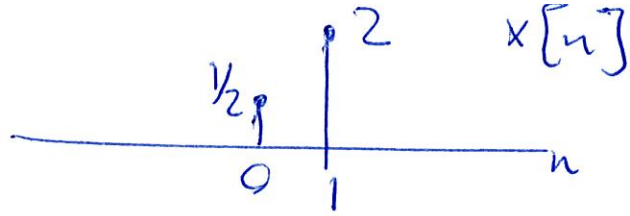
$x[n]$



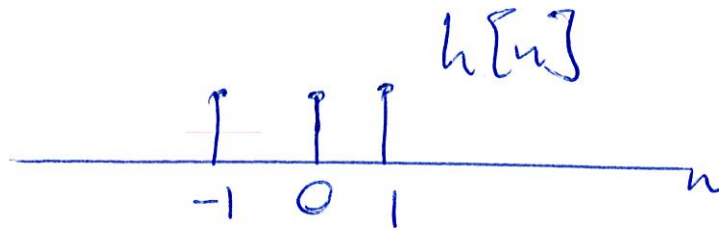
$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$= \sum_{k=0}^1 x[k] h[n-k] = \frac{1}{2} h[n] + 2 h[n-1]$$

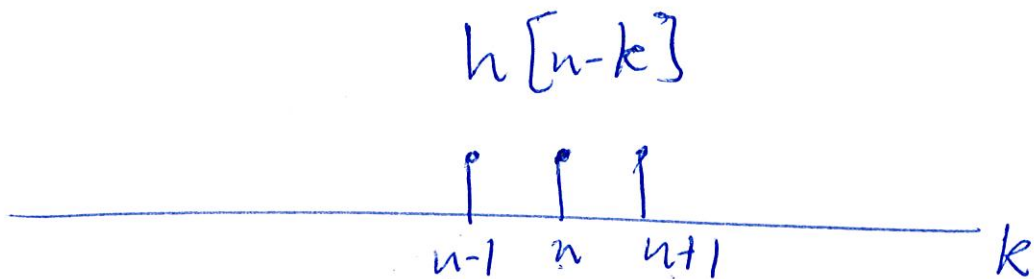
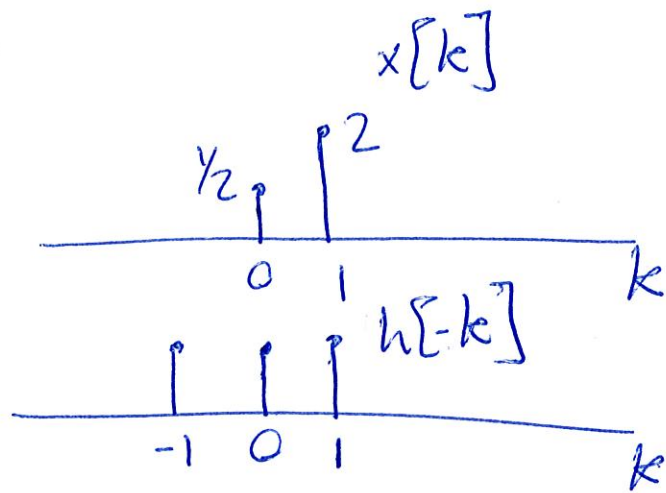




(7)



$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$



If  $n > 2$ ,  $y[n] = 0$

If  $n < -1$ ,  $y[n] = 0$

