

Quiz 3.

$$\omega_0^* = \omega_0.$$

a) $e^{j\omega_0 t}$ $a_1 = 1$ $a_k = 0 \quad k \neq 1.$

b) $\sin(\omega_0 t) = \frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j}$

$$\omega_0^* = \omega_0$$

$$a_1 = \frac{1}{2j} \quad a_{-1} = -\frac{1}{2j}$$

c) $\cos(2\omega_0 t)$ $\omega_0^* = 2\omega_0$

$$\cos(2\omega_0 t) = \frac{e^{j(2\omega_0)t} + e^{-j(2\omega_0)t}}{2}$$

$$a_1 = \frac{1}{2} \quad a_{-1} = \frac{1}{2} \quad a_k = 0 \quad k \neq \pm 1, -1.$$

d) $\sin(\omega_0 t) + \cos(2\omega_0 t)$ $\omega_0^* = \omega_0.$

$$\sin(\omega_0 t) + \cos(2\omega_0 t) = \frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j} + \frac{e^{j2\omega_0 t} + e^{-j2\omega_0 t}}{2}$$

$$a_1 = \frac{1}{2j} \quad a_{-1} = -\frac{1}{2j} \quad a_2 = \frac{1}{2} \quad a_{-2} = \frac{1}{2} \quad a_k = 0 \quad k \notin \{1, -1, 2, -2\}$$

e)



$$a_k = \frac{1}{T} \int x(t) e^{jk\omega_0 t} dt$$

$$T = 4, \omega_0 = \frac{2\pi}{4} = \frac{\pi}{2}$$

$$\Rightarrow a_k = \frac{1}{4} \int_{-1}^1 x(t) e^{jk\frac{\pi}{2}t} dt = \frac{1}{4} \int_{-1}^1 1 \cdot e^{jk\frac{\pi}{2}t} dt = \frac{1}{4} \left[\frac{e^{jk\frac{\pi}{2}t}}{jk\frac{\pi}{2}} \right]_{-1}^1$$

$$= \frac{1}{4} \frac{e^{jk\frac{\pi}{2}} - e^{-jk\frac{\pi}{2}}}{2j [k\pi]} = \frac{\sin k\frac{\pi}{2}}{4k\pi}$$

f)

$$a_0 = \frac{1}{4} \cdot 2 = \frac{1}{2}$$

f) Similar to (e)

$$a_k = \frac{1}{4} \left[\frac{e^{jk\frac{\pi}{2}t}}{jk\frac{\pi}{2}} \right]_{-\frac{1}{2}}^{\frac{1}{2}} = \frac{1}{4} \frac{e^{jk\frac{\pi}{4}} - e^{-jk\frac{\pi}{4}}}{2j (k\pi)} = \frac{\sin(\frac{\pi}{4})}{4k\pi}$$

g)

$$a_0 = \frac{1}{4} \cdot 1 = \frac{1}{4}$$

g. $x(t) = 1 \quad a_0 = 1 \quad a_k = 0 \quad k \neq 0$

h. $x(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$

$$a_k = \frac{1}{T} \int x(t) e^{jk\omega_0 t} dt \quad \omega_0 = \frac{2\pi}{T}$$

$$= \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x(t) e^{jk\frac{2\pi}{T}t} dt = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} \delta(t) e^{jk\omega_0 t} dt$$

$$= \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} \delta(t) dt = \frac{1}{T}$$

(i), (j) → check HW3 solutions.