# ECE 301: Signals and Systems Homework Assignment #6

Due on November 30, 2015

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Let  $x_1[n]$  be the discrete-time signal whose Fourier transform  $X_1(e^{jw})$  is depicted in Figure 1(a).

- (a) Consider the signal  $x_2[n]$  with Fourier transform  $X_2(e^{jw})$ , as illustrated in Figure 1(b). Express  $x_2[n]$  in terms of  $x_1[n]$ . (*Hint*: First express  $X_2(e^{jw})$  in terms of  $X_1(e^{jw})$ , and then use properties of the Fourier transform.)
- (b) Repeat part (a) for  $x_3[n]$  with Fourier transform  $X_3(e^{jw})$ , as shown in Figure 1(c).
- (c) Let

$$\alpha = \frac{\sum_{n=-\infty}^{\infty} n x_1[n]}{\sum_{n=-\infty}^{\infty} x_1[n]}$$

This quantity, which is the center of gravity of the signal  $x_1[n]$ , is usually referred to as the *delay time* of  $x_1[n]$ . Find  $\alpha$ . (You can do this without first determining  $x_1[n]$  explicitly.)

(d) Consider the signal  $x_4[n] = x_1[n] * h[n]$ , where

$$h[n] = \frac{\sin(\pi n/6)}{\pi n}$$

Sketch  $X_4(e^{jw})$ .



Figure 1: The graph of Fourier transforms of signals  $X_1(e^{jw}), X_2(e^{jw}), X_3(e^{jw})$ .

The signals x[n] and g[n] are known to have Fourier transforms  $X(e^{jw})$  and  $G(e^{jw})$ , respectively. Furthermore,  $X(e^{jw})$  and  $G(e^{jw})$  are related as follows:

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta}) G(e^{j(w-\theta)}) d\theta = 1 + e^{-jw}$$

- (a) If  $x[n] = (-1)^n$ , determine a sequence g[n] such that its Fourier transform  $G(e^{jw})$  satisfies the above equation. Are there other possible solutions for g[n]?
- (b) Repeat the previous part for  $x[n] = (\frac{1}{2})^n u[n]$ .

In lecture, we indicated that the continuous-time LTI system with impulse response

$$h(t) = \frac{W}{\pi} sinc(\frac{Wt}{\pi}) = \frac{sin(Wt)}{\pi t}$$

plays a very important role in LTI system analysis. The same is true of the discrete-time LTI system with impulse response

$$h[n] = \frac{W}{\pi} sinc(\frac{Wn}{\pi}) = \frac{sin(Wn)}{\pi n}$$

- (a) Determine and sketch the frequency response for the system with impulse response h[n].
- (b) Consider the signal

$$x[n] = \sin(\frac{\pi n}{8}) - 2\cos(\frac{\pi n}{4}).$$

Suppose that this signal is the input to LTI systems with the following impulse responses. Determine and sketch the frequency response of the output in each case.

(i) 
$$h[n] = \frac{\sin(\pi n/6)}{\pi n}$$
  
(ii)  $h[n] = \frac{\sin(\pi n/6)}{\pi n} + \frac{\sin(\pi n/2)}{\pi n}$   
(iii)  $h[n] = \frac{\sin(\pi n/6)\sin(\pi n/3)}{\pi^2 n^2}$   
(iv)  $h[n] = \frac{\sin(\pi n/6)\sin(\pi n/3)}{\pi n}$ 

(c) Consider an LTI system with unit sample response

$$h[n] = \frac{\sin(\pi n/3)}{\pi n}.$$

Determine and sketch the frequency response of the output in each case.

- (i) x[n] = the square wave depicted in Figure 2.
- (ii)  $x[n] = \sum_{k=-\infty}^{\infty} \delta[n-8k]$
- (iii)  $x[n] = (-1)^n$  times the square wave depicted in Figure 2.
- (iv)  $x[n] = \delta[n+1] + \delta[n-1]$



Figure 2: The square wave that construct x[n].

An LTI system X with impulse response h[n] and frequency response  $H(e^{jw})$  is known to have the property that, when  $-\pi \leq w_0 \leq \pi$ ,

 $\cos(w_0 n) \to w_0 \cos(w_0 n)$ 

- (a) Determine  $H(e^{jw})$ .
- (b) Determine h[n].