

Accelerated first-order methods for a class of semidefinite programs

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ICCOPT, July 27, 2022

① What structure? ... k -exactness

② How to use k -exactness? ... Strongly convex reformulation

③ Algorithms

④ Conclusion

- Semidefinite program

Related: Beck [2007], Beck et al. [2012], Wang and Kılınç-Karzan [2020]

- Semidefinite program

$$(\mathbf{SDP}) = \inf_{Y \in \mathbb{S}^{n+k}} \left\{ \langle M_0, Y \rangle : \begin{array}{l} \langle M_i, Y \rangle + d_i = 0, \forall i \in [m] \\ Y \succeq 0 \end{array} \right\}$$

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- Nonconvex and NP-hard

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- **Sneak peek:** “ k -exact” SDPs can be converted to easy instances of QMP

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Structural assumptions on SDP

- $$(\mathbf{SDP}) = \inf_{Y \in \mathbb{S}^{n+k}} \left\{ \langle M_0, Y \rangle : \begin{array}{l} \langle M_i, Y \rangle + d_i = 0, \forall i \in [m] \\ Y \succeq 0 \end{array} \right\}$$

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- Strong duality holds, both are solvable, there exists Y^* and γ^*

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- **This talk:** $W = \mathbb{R}^n \times \{0_k\}$ and $Y_{W^\perp}^* = I_k$

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Motivation

- SDP relaxation of QMP in $X \in \mathbb{R}^{n \times k}$

Related: Ben-Tal and Nemirovski [2001], Beck [2007], Wang and Kılınç-Karzan [2022]

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- Let $Y(X) := \begin{pmatrix} XX^\top & X \\ X^\top & I_k \end{pmatrix}$

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$$q_i(X) = \langle M_i, Y(X) \rangle = \left\langle \begin{pmatrix} A_i & B_i \\ B_i^\top & c_i I_k/k \end{pmatrix}, \begin{pmatrix} XX^\top & X \\ X^\top & I_k \end{pmatrix} \right\rangle$$

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Know $Y_{W^\perp}^* = I_k$

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Recap of structural assumptions

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- ② How to use k -exactness? ... Strongly convex reformulation
- ③ Algorithms
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- Take the Lagrangian to get minimax problem without constraints

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$$A(\gamma) = \text{top-left block of } M(\gamma)$$

Deriving a strongly convex minimax problem

- **Thought experiment:** strong duality + strict complementarity implies

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Theorem (Certificate of strict compl. gives strongly conv. reform.)

Suppose $\gamma^* \in \mathcal{C} \subseteq \mathbb{R}^m$ and $A(\gamma) \succ 0$ for all $\gamma \in \mathcal{C}$, then

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- **Algorithm:**
 - Construct \mathcal{C}

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Suppose $\gamma^* \in \mathcal{C} \subseteq \mathbb{R}^m$ and $A(\gamma) \succ 0$ for all $\gamma \in \mathcal{C}$, then

$$X^* = \arg \min_{X \in \mathbb{R}^{n \times k}} \max_{\gamma \in \mathcal{C}} q(\gamma, X)$$

- **Algorithm:**
 - Construct \mathcal{C}
 - Solve strongly convex quadratic matrix minimax problem (QMMP)

① What structure? ... k -exactness

② How to use k -exactness? ... Strongly convex reformulation

③ Algorithms

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- How to solve strongly convex QMMP?

$$\arg \min_{X \in \mathbb{R}^{n \times k}} \max_{\gamma \in \mathcal{C}} q(\gamma, X)$$

Related: Nesterov [2005], Devolder et al. [2013, 2014], Nesterov [2018]

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Theorem (CautiousAGD)

CautiousAGD produces iterates X_t such that

$$\max_{\gamma \in \mathcal{C}} q(\gamma, X_t) \leq \min_X \max_{\gamma \in \mathcal{C}} q(\gamma, X) + \epsilon$$

after $O(\log(\epsilon^{-1}))$ iterations, $O(m\epsilon^{-1/2})$ matrix-vector products per iteration

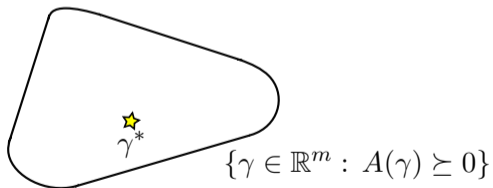
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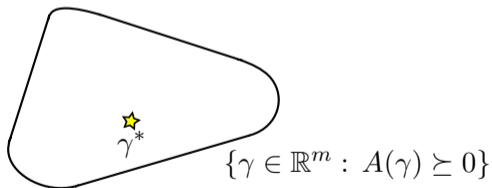
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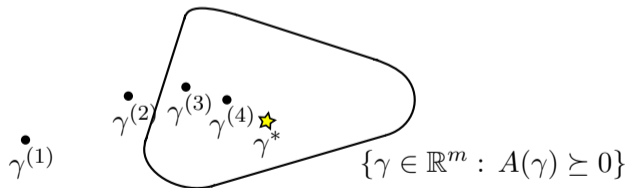


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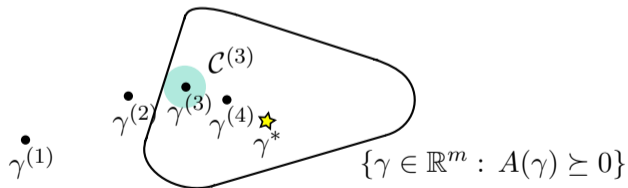
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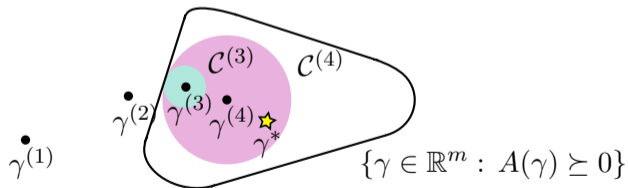
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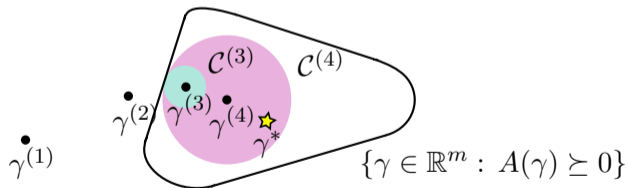
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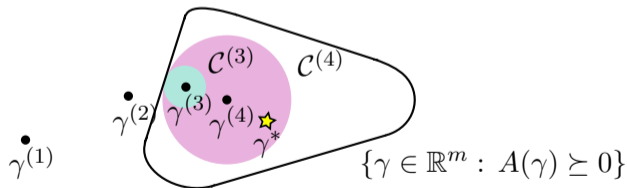
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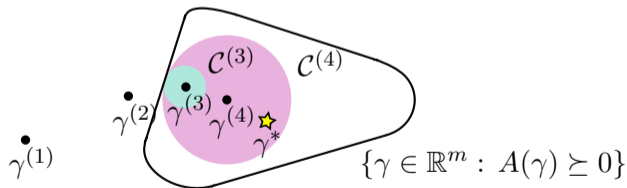
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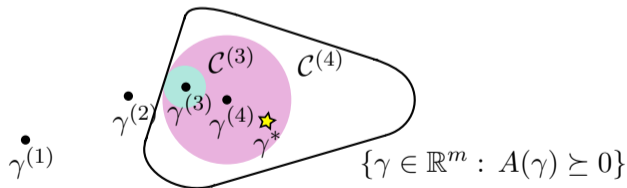


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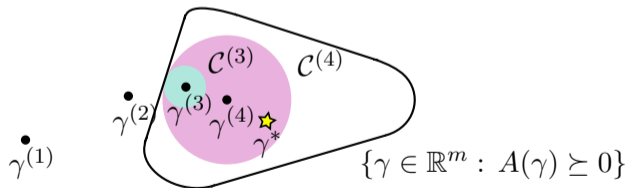


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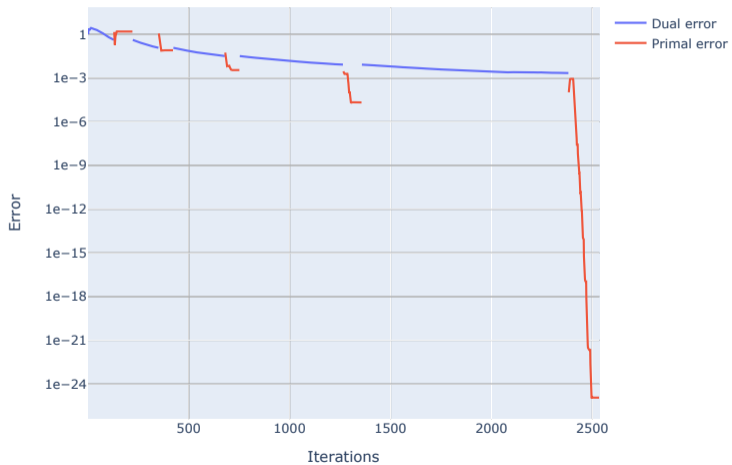


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CertSDP convergence behavior



Theorem (CertSDP)

CertSDP produces iterates X_t such that

$$\left\langle M_0, \begin{pmatrix} X_t X_t^\top & X_t \\ X_t^\top & I_k \end{pmatrix} \right\rangle \leq \text{Opt}_{\text{SDP}} + \epsilon \quad \left\| \left(\left\langle M_i, \begin{pmatrix} X_t X_t^\top & X_t \\ X_t^\top & I_k \end{pmatrix} \right\rangle + d_i \right)_i \right\|_2 \leq \epsilon$$

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- **Storage:** $O(m + nk)$ storage

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Thank you! Questions?

<https://arxiv.org/abs/2206.00224>

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